## VAUTOMATIONDIRECT\$

## Motion Control

## Sureño <br> servo

## Surestep



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## Sure

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## Surestep Stepping System Overview

## High-performance microstepping drives with high-torque stepping motors

SureStep stepping systems provide simple and accurate control of position and speed where open-loop control and cost are considerations. Pulses (or "step" and "direction" signals) from the DirectLOGIC family of PLCs or other indexers and motion controllers are "translated" by the microstepping drive into precise movement of the stepping motor shaft. The SureStep stepping motors use 2-phase technology with 200 full steps per revolution or $1.8^{\circ}$ per full step. Older type stepping motor drives, which operate stepping motors in full step mode, can result in stalling or lost motion due to potential problems with low speed mechanical vibration (usually between 100 to 200 RPM). To minimize this vibration problem, the SureStep microstepping drives use advanced microstepping technology to smooth the motor motion and stepping response.

## Standards and Agency Approvals $E$

How fast can my system go?

| Maximum Potential Speed Chart (rpm) * |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| PLC |  | Surestep Drive Steps/Rev Selection ** |  |  |  |
| Model | Fastest Output | $\begin{gathered} 400 \\ \text { Steps/Rev } \end{gathered}$ | $\begin{array}{\|c\|} 1000 \\ \text { Steps/Rev } \end{array}$ | $\begin{gathered} 2000 \\ \text { Steps/Rev } \end{gathered}$ | $\begin{array}{\|c\|} \hline 10,000 \\ \text { Steps/Rev } \end{array}$ |
| DL05, DL105 | 7 kHz | 1,050 | 420 | 210 | 42 |
| DL06 | 10 kHz | 1,500 | 600 | 300 | 60 |
| $\begin{gathered} \mathrm{H} 0 / \mathrm{H} 2 / \mathrm{H} 4 / \mathrm{T} 1 \mathrm{H} \\ \text {-CTRIO } \end{gathered}$ | 25 kHz | 3,750 | 1,500 | 750 | 150 |
| $\underline{\text { H2-CTRIO2 }}$ | 250 kHz | 37,500 | 15,000 | 7,500 | 1,500 |
| P3-HSO | 1 MHz | 150,000 | 60,000 | 30,000 | 6,000 |
| * These speeds are theoretical maximums. See torque curves of specific motors for their rpm limits. <br> ** Full step (200 steps/rev) will allow higher top speed. <br> Full stepping, however, can create vibration at low speed. |  |  |  |  |  |

The STP-DRV-4035 has selectable microstep resolutions of 400 (half-step); 1,000 (each full step $\div 5$ microsteps); 2,000 $(\div 10)$; or $10,000(\div 50)$.
The STP-DRV-6575 has selectable resolutions of 200 (full-step); 400 (half-step); 2,000; 5,000; 12,800; or 20,000 steps per revolution.
The advanced drives (STP-DRV-4805, STP-DRV-80100) have soft-ware-selectable resolutions ranging from 200 (full step) to 51,200 ( $\div 256$ ) steps per revolution.
The advanced drives can operate with traditional high-speed inputs, but can also be commanded via $0-5 \mathrm{~V}$ analog input. They have an internal indexer that can accomplish point-to-point moves controlled via ASCII communication.

## FREE configuration software!

SureStep Pro configuration software is available that makes setting parameters a snap for the advanced drives (STP-DRV-4850 \& STP-DRV-80100)! Download free from our website:
http://support.automationdirect.com/products/surestep.html

Stepping Motor RPM $=(\mathrm{A} \div \mathrm{B}) \times(60$ seconds/minute $)$
Where: $A=$ PLC output frequency (pulses per second)
$B=$ microstepping resolution selection (steps/revolution)

| Maximum RPM = |  | Steps/Sec <br> A |  | Steps/Rev <br> B |  | Sec/Min |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Example 1: | 1,500 = | 10,000 | $\div$ | 400 | X | 60 |
| DL06 with 10 kHz Built-in Pulse Output |  |  |  |  |  |  |
| Example 2: | 3,750 = | 25,000 | $\div$ | 400 | X | 60 |

## Four components to make a complete system

Choose a drive, motor, motor extension cable and power supply


## Sure step-Stepping System Overview

## Stepping System : Head to Head

## AutomationDirect LS』 Competition

## Hey - I can do the math! - AutomationDirect

A complete 2-axis SureStep ${ }^{\text {rt }}$ Stepping System for less than just the competition's stepping drives.


## High-torque stepping motors with 1-ft. cable and 4-wire locking connector

The SureStep stepping family has twenty high-torque motors to handle a wide range of automation applications such as woodworking, assembly, and test machines. The motors are available in both single-shaft and dual-shaft configurations. Our square frame or "high-torque" style stepping motors are the latest technology, resulting in the best torque to volume. We have NEMA 17, 23, and 34 mounting flanges and holding torque ranges from 61 to 1288 oz-in. Optional 20 -foot extension cables with locking connectors are available to interface any of the stepping motors to the microstepping drive. The extension cables can be easily cut to length, if desired.

Holding Torque (oz•in)
High Torque Motors (MTR)


Holding Torque (oz:in)


## High-performance microstepping drive

## SureStep microstepping drives <br> (STP-DRV-4035 \& STP-DRV-6575)

- Two models available
- Standard high-speed pulse input (pulse and direction)
- On-board or removable screw terminals for easy hook-up
- Optically-isolated inputs ready for +5 VDC logic from DirectLOGIC PLCs, or 5-24 VDC (depending on model).
- No software or add-on resistors required for drive configuration; dipswitch and/or rotary-dial set-up
- Dipswitch used for built-in self-test, microstep resolution selection, current level selection, and optional idle current reduction.


## SureStep advanced microstepping drives

 (STP-DRV-4850 \& STP-DRV-80100)All the features of the high-performance drive, plus:

- Software configurable
- 200-51,200 microsteps (software selectable)
- High-speed pulse input (Quadrature, cw/ccw, pulse/direction)
- Analog velocity mode (0-5v or potentiometer)
- Internal indexer (point-to-point moves via ASCII command)


## Linear power supplies

- $32 \mathrm{~V} @ 4 \mathrm{~A}, 48 \mathrm{~V} @ 5 \mathrm{~A}, 48 \mathrm{~V} @ 10 \mathrm{~A}, 70 \mathrm{~V} @ 5 \mathrm{~A}$
- Input and output fuses included on power supplies
- Includes 5 VDC Logic supply for all low voltage signals


## Surestep ${ }^{\text {step }}$ Choose your SureStep System

## 1. Choose a motor

Determine the torque and speed required by your application. Then look at the motor speed-torque curves in the "SureStep Stepping System Motors" section of this catalog chapter. Choose a motor that can run your application with plenty of speed and torque reserve (most stepper systems should have a $100 \%$ safety margin for torque).

NEMA 17, 23 and 34 mounting flanges

Twenty bipolar step motors to cover a wide range of applications


Holding torque ranges from 61 to 1288 oz•in Single-shaft and Dual-shaft models available

1-ft cable (4-wire) with locking connector on the end

Square frame style produces high torque and achieves best torque to volume ratio

## 2. Choose a motor extension cable

Our 20-ft motor extension cables have a locking connector that mates up to the motor cable. The extension cables allow you to quickly connect the motor to the drive without having to splice wires or cut any cables. If you chose an STP-MTR-xxxx motor, select an STP-EXT-020 cable.
If you chose an STP-MTRH-xxxx motor, select an STP-EXTH-020 cable.
(The " H " motors and cable can handle higher motor current)

## 3. Choose a drive

This chart is a quick selection guide. For a full list of features, check out the Technical Info later in this chapter.

| What you need | STP- <br> DRV- <br> 4035 | $\begin{aligned} & \text { STP- } \\ & \text { DRV- } \\ & 4850 \end{aligned}$ | $\begin{aligned} & \text { STP- } \\ & \text { DRV- } \\ & 6575 \end{aligned}$ | $\begin{aligned} & \hline \text { STP- } \\ & \text { DRV- } \\ & 80100 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| 32 V Speed-Torque Curve (from Step 1) | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| 48 V Speed-Torque Curve (from Step 1) | - | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| 70V Speed-Torque Curve (from Step 1) | - | - | - | $\checkmark$ |
| Pulse \& Direction Input | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| More than 3.5A/motor phase | - | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| More than 5A/motor phase ("H" motors) | - | - | $\checkmark$ | $\checkmark$ |
| Internal Indexing (Drive can move from Point A to Point B with a serial communication command) | - | $\checkmark$ | - | $\checkmark$ |
| Analog Velocity Input | - | $\checkmark$ | - | $\checkmark$ |



Optional idle current reduction

Adjustable microstep
resolutions
0.1 to 10 amps (depending on drive model)


## 4. Choose a power supply

Since all SureStep motors can operate at $32 \mathrm{~V}, 48 \mathrm{~V}$, and 70 V , the selection of a power supply is dependent on the selected speedtorque curve of the motor and on the selection of drive. Choose a power supply that matches the desired speed-torque curve
and stays within the voltage limit of the selected drive. Each power supply has incoming AC and outgoing DC fusing. There is also an electronically overload protected 5 V supply for all your logic needs.

Permissible Drive/Power Supply Combinations

| Power Supply | STP- <br> PWR- <br> 3204 | STP- <br> PWR- <br> 4805 | STP- <br> PWR- <br> 4810 | STP- <br> PWR- <br> 7005 |
| :---: | :---: | :---: | :---: | :---: |
| Drive |  |  |  |  |
| STP-DRV-4035 | $\checkmark$ | - | - | - |
| STP-DRV-4850 | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| STP-DRV-6575 | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| STP-DRV-80100 | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

For systems that use multiple drives and only one power supply, please read our SureStep User Manual (under "Product Documentation") to properly size multiple systems.
$32 \mathrm{~V}, 48 \mathrm{~V}$ and 70 V linear supplies

Power ON LEDs

Unregulated linear supplies perfect for stepper systems

Input and output fusing included
 regulated logic power


NEMA Step Motor

120 or 240 VAC, 50/60 Hz power input (switch

Screw terminal AC input and DC output connections ctable)

Motor Extension Cable


# Surestep ${ }^{\circ}$ Stepping System Components 



## SureStep stepping system includes:

- Four step motor power supplies
- Two DIP-switch configurable microstepping drives
- Two software configurable advanced microstepping drives
- Two motor extension cables
- Twenty step motors (NEMA 17, 23, 34 frame sizes; single \& dual shaft)


## Standard stepper drive features

(STP-DRV-4035 \& STP-DRV-6575)

- Low cost, digital step motor driver in compact package
- Operates from Step \& Direction signals, or Step CW \& Step CCW (jumper selectable)
- Fault output (-6575 only) \& Enable input
- Optically isolated I/O
- Digital filters prevent position error from electrical noise on
command signals; jumper selectable: 150 kHz or 2 MHz (-6575 only)
- Rotary or DIP switch easily selects from many popular motors
- Electronic damping and anti-resonance (-6575 only)
- Automatic idle current reduction to reduce heat when motor is not moving; switch selectable: $50 \%$ or $90 \%$ of running current
- Switch selectable step resolution: (-DRV-4035) 400-10,000 steps per revolution; (-DRV-6575) 200-20,000 steps per revolution
- Switch selectable microstep emulation provides smoother, more reliable motion in full and half step modes
- Automatic self test (switch selectable)
- Operates from a 24-65 VDC or 12-40 VDC power supply, depending upon model
- Running current from 0.5-7.5A


## Advanced stepper drive features

(STP-DRV-4850 \& STP-DRV-80100)

- Max 5A, 48V and max 10A, 80V models available
- Software configurable
- Programmable microsteps
- Internal indexer (via ASCII commands)
- Self test feature
- Idle current reduction
- Anti-resonance
- Torque ripple smoothing
- Step, analog, \& serial communication inputs
- Serial communications allow point-to-point positioning


## Motor features

- High torque, 2-phase, bipolar, $1.8^{\circ}$ per step, 4-lead
- Available in single-shaft and dual-shaft models
- Connectorized
- (6) NEMA 17 motors
- (6) NEMA 23 motors
- (8) NEMA 34 motors


## Power supply features

- Linear, unregulated DC power supplies
- 120/240 VAC selectable input
- $32 \mathrm{~V}, 48 \mathrm{~V}, 70 \mathrm{~V}$ DC output models available
- All models have additional 5VDC, 500 mA reģulated loģic supply
- Fusing included for both incoming AC and outgoing DC
- 5 V supply has electronic overload protection


Single-shaft or Dual-shaft


Typical Wiring Diagram


Surestep Power Supply / Drive Compathility

| Drive $^{(1)(2)}$ | Recommended Power Supply(1)(2) |  |  |  |
| :--- | :---: | :---: | :---: | :---: |
| Model \# | STP-PWR <br> -3204 | STP-PWR <br> -4805 | STP-PWR <br> -4810 | STP-PWR <br> -7005 |
| STP-DRV-4035 | $\checkmark$ | $N 0$ | No | No |
| STP-DRV-4850 | $\checkmark$ | $\checkmark$ | $\checkmark$ | No |
| STP-DRV-6575 | $\checkmark$ | $\checkmark$ | $\checkmark$ | No |
| STP-DRV-80100 | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

1) Do NOT use a power supply that exceeds the drive's input voltage range. If using a non-STP linear power supply, ensure that the unloaded voltage does not float above the drive's maximum input range.
2) For best performance, use the lowest voltage power supply that supplies the required speed and torque.

| Surestep Drive / Motor Compatibility |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Motor ${ }^{(1)(2)}$ |  |  | Recommended Drive ${ }^{(1)}$ |  |  |  |
| Model \# (1)(2) |  |  | $\begin{array}{\|l\|l\|} \hline \text { STP-DRV } \\ -4035(1) \end{array}$ | $\begin{aligned} & \text { STP-DRV } \\ & -4850(1) \end{aligned}$ | $\begin{aligned} & \text { STP-DRV } \\ & -6575(1) \end{aligned}$ | $\begin{gathered} \text { STP-DRV } \\ -80100(1) \end{gathered}$ |
| STP-MTR-17040(D) | 1.7 |  | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| STP-MTR-17048(D) | 2.0 |  | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| STP-MTR-17060(D) | 2.0 |  | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| STP-MTR-23055(D) | 2.8 |  | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| STP-MTR-23079(D) | 2.8 |  | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| STP-MTR-34066(D) | 2.8 |  | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| STP-MTRH-23079(D) | 5.6 |  |  |  | $\checkmark$ | $\checkmark$ |
| STP-MTRH-34066(D) | 6.3 |  |  |  | $\checkmark$ | $\checkmark$ |
| STP-MTRH-34097(D) | 6.3 |  |  |  | $\checkmark$ | $\checkmark$ |
| STP-MTRH-34127(D) | 6.3 |  |  |  | $\checkmark$ | $\checkmark$ |
| 1) The combinations above will perform according to the published speed/torque curves. However, any STP motor can be used with any STP drive. Using a motor with a current rating higher than the drive's output rating will proportionally limit the motor torque. <br> 2) MTR motors have connectors compatible with the EXT extension cables. MTRH motors have connectors compatible with the EXTH extension cables. |  |  |  |  |  |  |
|  |  |  |  |  |  |  |

## Surestep ${ }^{\circ}$ Stepping System Drives

SureStep ${ }^{\circledR}$ Microstepping Drives Overview

| SurgStep Series - Miorostepping Drives Features Comparison |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Drive Model |  | Standard Microstepping Drives |  | Advanced Microstepping Drives |  |
|  |  | STP-DRV-6575 | STP-DRV-4035 | STP-DRV-4850 | STP-DRV-80100 |
| Price |  | \$89.00 | \$155.00 | \$215.00 | \$265.00 |
| Drive Type |  | Microstepping drive with pulse input |  | Advanced microstepping drive with pulse or analog input, serial communication; includes programming/communication cable STP-232RJ11-CBL |  |
|  |  | enclosed | open-frame | enclosed |  |
| Output Current |  | 1.0-7.5 A/phase | 0.4-3.5 A/phase | 0.1-5 A/phase | 0.1-10 A/phase |
| Input Voltage |  | nominal: 24-65 VDC range: $20-75 \mathrm{VDC}$ | nominal: 12-32 VDC range: 12-42 VDC | nominal: 24-48 VDC <br> range: $18-53$ VDC | nominal: 24-80 VDC range: $18-88 \mathrm{VDC}$ |
| Configuration Method |  | rotary dial, dip switches, jumpers | dip switches | SureStep Pro software (included) |  |
| Amplifier Type |  | MOSFET, dual H-bridge, 4-quadrant | MOSFET, dual H-bridge, bipolar chopper | MOSFET, dual H-bridge, 4-quadrant |  |
| Current Control |  | 4-state PWM @ 20 kHz | 4-state PWM 20 kHz | 4-state PWM @ 20 kHz | 4-state PWM @ 20 kHz |
| Microstep Resolution |  | dipswitch selectable | dipswitch selectable | software selectable | software selectable |
|  |  | 200 to 20,000 steps/rev | 400 to 10,000 steps/rev | 200 to 51200 steps/rev |  |
| Modes of Operation | Step \& Dir | YES | YES | YES | YES |
|  | CW/CCW | YES | n/a | YES | YES |
|  | A/B Quad | n/a | n/a | YES | YES |
|  | Oscillator | n/a | n/a | YES | YES |
|  | Serial Indexing | n/a | n/a | YES | YES |
| Digital Input Signals | Step/Pulse | step \& direction, CW/CCW step | step \& direction | step \& direction, CW/CCW step, $A / B$ quadrature, run/stop \& direction, jog CW/CCW, CW/CCW limits |  |
|  | Direction |  |  |  |  |
|  | Enable | motor disable | motor disable | motor enable, alarm reset, speed select (oscillator mode) |  |
| Analog Input |  | n/a | n/a | speed control |  |
| Output Signal |  | fault | n/a | fault, motion, tach |  |
| Communication Interface |  | n/a | n/a | YES (programming/communication cable included) |  |
| Non-volatile Memory Storage |  | n/a | n/a | YES |  |
| Idle Current Reduction |  | YES | YES | YES |  |
| Self Test |  | YES | YES | YES |  |
| Additional Features |  | Load inertia (anti-resonance \& damping feature to improve motor performance) <br> Step pulse noise filter | n/a | Anti-resonance (Electronic Damping)Auto setupMicrostep emulationTorque ripple smoothing(allows for fine adjustment of phase in the range 0.25 to 1.5 rps )Waveform (command signal) smoothing |  |
| Refer to Specifications Tables for detailed specifications |  |  |  |  |  |

## Company Information

## Sure step $^{\circ}$ Stepping System Drives

## SureStep ${ }^{\circledR}$ Standard Microstepping Drives



| SureStep Series Specifications - Standard Microstepping Drives |  |  |  |
| :---: | :---: | :---: | :---: |
| Microstepping Drive |  | STP-DRV-6575 | STP-DRV-4035 |
| Drive Type |  | Microstepping drive with pulse input | Microstepping drive with pulse input |
| Output Current |  | Selectable from 1.0-7.5 A/phase (peak of sine) | Selectable from 0.4 to 3.5 A/phase (maximum output power is 140W) |
| Input Voltage (external p/s required) |  | Nominal: 24-65 VDC Range: $20-75$ VDC | Nominal: 12-32 VDC <br> Range: 12-42 VDC (including ripple voltage) |
| Configuration Method |  | Rotary dial, DIP switches, jumpers | DIP switches |
| Amplifier Type |  | MOSFET, dual H-bridge, 4-quadrant | MOSFET, dual H-bridge, bipolar chopper |
| Current Control |  | 4-state PWM @ 20 kHz | 4-state PWM @ 20 kHz |
| Protection |  | n/a | n/a |
| Recommended Input Fusing |  | Fuse: 7A fast-acting; ADC \#ACG7; Holder: ADC \# DN-F6L110 | Fuse: 4A fast-acting; ADC \# ACG4; Holder: ADC \# DN-F6L110 |
| Input <br> Signals | Input Circuit | 5-24 VDC nominal (range: 4-30 VDC); optically isolated, differential. | Opto-coupler input with 440 resistance ( 5 to 15 mA input current); Logic Low is input 0.8 VDC or less; Logic High is input 4VDC or higher. |
|  | Step/Pulse | Minimum pulse width $=0.25 \mu \mathrm{~s}$. Maximum pulse frequency $=$ 150 kHz or 2 MHz (user selectable). <br> FUNCTIONS: step \& direction, CW/CCW step | Motor steps on falling edge of pulse and minimum pulse width is $0.5 \mu \mathrm{~s}$ (1MHz) |
|  | Direction |  | Needs to change at least 2 microseconds before a step pulse is sent |
|  | Enable | FUNCTION: disable motor when closed | Logic 1 will disable current to the motor (current is enabled with no hook-up or logic 0) |
|  | Analog | n/a | n/a |
| Output Signal |  | $30 \mathrm{VDC} / 80 \mathrm{~mA}$ max, optically isolated photodarlington, sinking or sourcing. <br> Function = closes on drive fault. | n/a |
| Features | Current Reduction | Reduce power consumption and heat generation by limiting motor running current to $100 \%, 90 \%$, or $80 \%$ of maximum. Current should be increased to $120 \%$ if microstepping. (Torque is reduced/increased by the same \%.) | n/a |
|  | Idle Current Reduction | $90 \%$ or $50 \%$ of running current. <br> (Holding torque is reduced by the same \%.) | $0 \%$ or $50 \%$ reduction <br> (idle current setting is active if motor is at rest for 1 second or more) |
|  | Microstep Resolution | $20000,12800,5000,2000,400$ smooth, 400, 200 smooth, or 200 steps/rev. | 400 (200x2), 1,000 (200x5), 2,000 (200x10), or 10,000 (200x50) steps/rev |
|  | Phase Current Setting | (1.3-6.3) $\times 80 \%-120 \%$ DIP switch selectable | 0.4 to 3.5 A/phase with 32 selectable levels |
|  | Self Test | Automatically rotates the motor back and forth two turns in each direction in order to confirm that the motor is operational | Uses half-step to rotate $1 / 2$ revolution in each direction at 100 steps/second |
|  | Step Pulse Noise Filter | Select 150 kHz or 2 MHz | n/a |
|  | Load Inertia | Set motor and load inertia range to 0-4x or 5-10x. | n/a |
| Connectors |  | Removable screw terminal blocks. Motor \& Power Supply: 30-12 AWG; Signals: 30-14 AWG | Screw terminal blocks with AWG 18 maximum wire size |
| Maximum Humidity |  | 90\% non-condensing | 90\% non-condensing |
| Storage/Ambient Temperature |  | 0 to $50^{\circ} \mathrm{C}$ [32 to $122^{\circ} \mathrm{F}$ ] (mount to suitable heat sink) | -20 to $80^{\circ} \mathrm{C}$ [-4 to $\left.176{ }^{\circ} \mathrm{F}\right]$ |
| Operating Temperature |  | 0 to $85^{\circ} \mathrm{C}$ [32 to $185^{\circ} \mathrm{F}$ ( (interior of electronics section) | 0 to $55^{\circ} \mathrm{C}\left[32\right.$ to $\left.131{ }^{\circ} \mathrm{F}\right]$ recommended; $70^{\circ} \mathrm{C}\left[158{ }^{\circ} \mathrm{F}\right]$ maximum |
| Drive Cooling Method |  | Natural convection (mount drive to metal surface) | Natural convection (mount drive to metal surface to dissipate heat) |
| Mounting |  | (2) \#6 screws to mount wide or narrow side to metal surface | (4) \#4 screws to mount on wide side; (2) \#4 screws to mount on narrow side |
| Weight |  | 10.802 [ 306 g ] - (including mating connectors) | 9.3 oz. [264 g] |
| Agency Approvals |  | CE (EMC \& LVD); RoHS | CE (complies with EN55011A \& EN50082-1 (1992)), RoHS |

## Sure stepa $^{\circ}$ Stepping System Drives

SureStep ${ }^{\circledR}$ Advanced Microstepping Drives



## Surestepo $^{\text {step }}$ Stepping System Drives

## SureStep ${ }^{\circledR}$ Microstepping Drives Accessories

## Braking Accessories

If you plan to use a regulated or switching power supply, you might encounter problems from regeneration. As a load rapidly decelerates from a high speed, much of the kinetic energy of that load is transferred back to the motor. This energy is then pushed back to the drive and power supply, resulting in increased system voltage. If there is enough overhauling load on the motor, the DC voltage will go above the drive and/or power supply limits.
This can trip the overvoltage protection of a switching power supply or a drive, and cause it to shut down.
To solve this problem, AutomationDirect offers a regeneration clamp and a braking resistor as optional accessories. The regen clamp has a built-in 50W braking resistor. For additional braking power (larger overhauling loads), an optional 100W braking resistor is also available.

## Regeneration Clamp Description

As with most stepper systems, a clamp circuit is often required to limit increased power supply bus voltage when the motor is decelerating under load. This is commonly referred to as "regeneration," which is what happens when DC motors are driven by their load. During regeneration, the DC motor can produce enough voltage to actually exceed the input power supply voltage.
With a Regen Clamp, one or more stepper drives can be protected from "Over Voltage" conditions by placing the clamp module between the power supply and the drive. The clamp tracks the input power supply, and will operate from 24 to 80 volts. No adjustments are needed.
The Regen Clamp is designed to handle a wide range of conditions. The voltage input matches the needs of the SureStep stepper drives by providing 24 to 80 VDC capabilities, and external power resistors can be added for even greater continuous power requirements. The clamp modules are small and compact to minimize impact on the system design. More than one stepper drive can be connected to the clamp module with the potential to handle an entire multi-axis sytem.


Braking Resistor

## Regeneration Clamp Features

- Built-in 50W power resistor for more continuous current handling (optional 100W resistor is also available)
- Mounted on a heat sink
- Voltage range: 24-80 VDC; no user adjustments required
- Power: 50W continuous; 800W peak
- Wire connection: 6-pin screw terminal block; 12-18 AWG wire.
- Indicators (LED):

Green = power supply voltage is present
Red = clamp is operating (usually when stepper is decelerating)

- Protection: The external power supply is internally connected to an "Input Diode" in the regen clamp that protects the power supply from high regeneration voltages. This diode protects the system from connecting the power supply in reverse. If the clamp circuit fails, the diode will continue to protect the power supply from over-voltage.
- RoHS

SureStep Series Specifications - Microstepping Drives Optional Accessories

| Part Number | Price | Description |
| :--- | :---: | :--- |
| STP-DRVA-RC-050 * | $\$ 99.00$ | Regen Clamp: use with DC-powered stepper \& servo drives; 50W, 24-80 VDC |
| STP-DRVA-BR-100 | $\$ 49.00$ | Braking Resistor: use with STP-DRV-RC-050 regen clamp; 100W, 10 ohms |
| Do not use the regeneration clamp in an atmosphere containing corrosive gases. |  |  |

## Surestepo $_{\text {Stepping System Drives }}$

## SureStep ${ }^{\circledR}$ Microstepping Drives Accessories

## SureStep Pro Drive Configuration Software - for Advanced Stepper Drives

## Free Download

SureStep Pro configuration software is available as a free download from our website for SureStep advanced drives (STP-DRV-4850 \& -80100).

- Used for easy configuration and setup of the drive, including drive, motion control mode, I/O, motor.
- Serial command lanģuaģe for motor drive control via serial port; eliminates the need for separate motion controllers or indexers; provides easy interface to other industrial devices such as PCs, PLCs and HMIs.
- Easily use the ASCII output commands from most of our PLCs to enable indexing capability.
- Help files include technical data, application information, advanced setup, serial command instructions.
- Runs on 32-bit/64-bit Windows 7 and XP operating systems.


| SureStep Drive Gonfiguration Softwaire - for Advanced Stepper Drives |  |  |
| :--- | :--- | :--- |
| Part Number | Price | Description |
| STP-PRO * | $\$ 9.00$ | Windows-based contiguration software for use with SureStep STP-DRV-4850 and STP-DRV-80100 advanced stepper drives. Requires Windows XP or <br> Windows 7 ( (32 or 64-bit) operating system, minimum 12MB hard drive Space, and RS-232 port (sottware also compatible with USB-RS232 adapter). |
| * Available for purchase on CD or can be downloaded for free from AutomationDirect Web site (www.AutomationDirect. com). |  |  |

## Sure $_{\text {stel }}{ }^{\circ}$ Stepping System Drives

SureStep ${ }^{\circledR}$ Microstepping Drives Dimensions

Dimensions $=$ in [mm]

## STP-DRV-6575



## STP-DRVA-BR-100



STP-DRVA-RC-050


## VAUTOMATIONDIRECT



## If it's in your cabinet, it's online at: www.AutomationDirect.com Tens of thousands of in-stock quality items

Starting with the enclosure, we carry everything you need to build an electrical control system, right down to the wire and tools. And we have the devices that go in the panel, such as logic controllers, HMI, drives, relays, and motor controls. If you're maintaining existing systems, we've got great prices on MRO parts such as circuit breakers, fuses, motors, pneumatics and pilot devices. In addition to our catalog all our products are available to order 24/7 at www.automationdirect.com

## Value Pricing

Our everyday prices on industrial control products are well below the list prices of more traditional automation companies because, with our direct business model and focus on high efficiency, AutomatoonDirect has the lowest overhead in the industry. We pass the savings on to you by offering high-quality products at low prices.

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Almost 99\% of AutomationDirect customers responding to surveys say they would recommend us to someone else, and they do! And we've been voted tops in service by independent magazine surveys 13 years running.

## FREE \& Fast Shipping*

The majority of our products are stocked for same-day shipping, when you place your order by 6 p.m. EST.

[^0]
## Surestep ${ }^{\circ}$ Stepping System Motors

## SureStep ${ }^{\circledR}$ Stepping Motors

| Surestep Series Part Numbers - Gonnectorized Bipolar Stepping Motors |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Bipolar <br> Stepping Motors | High Torque Motors |  |  |  |  |  |  |  |  |  |  |  | Higher Torque Motors |  |  |  |  |  |  |  |
|  | $\begin{aligned} & \text { 先 } O \\ & \sum_{i}^{\prime} \\ & i_{i}^{\prime} \end{aligned}$ |  | $\sum_{i=1}^{\sum_{i}^{\prime}} \underset{\sim}{\infty}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | $\frac{1}{c}$ $\sum_{i}^{c}$ $\vdots$ $\vdots$ $\vdots$ |  |
| Price | \$18.00 | \$22.00 | \$22.00 | \$26.00 | \$35.50 | \$39.50 | \$35.50 | \$40.00 | \$46.50 | \$51.00 | \$111.00 | \$126.00 | \$51.50 | \$56.00 | \$124.00 | \$139.00 | \$140.00 | \$155.00 | \$167.00 | \$167.00 |
| Shaft Type | single | dual | single | dual | single | dual | single | dual | single | dual | single | dual | single | dual | single | dual | single | dual | single | dual |


| Surestep Series Specifioations - Bonnectorized Bipolar Stepping Motors |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Bipolar Stepping Motors |  | High Torque Motors |  |  |  |  |  | Higher Torque Motors |  |  |  |
|  |  | $\begin{aligned} & \text { STP-MTR- } \\ & 17040(D) \end{aligned}$ | $\begin{aligned} & \text { STP-MTR- } \\ & \text { 17048(D) } \end{aligned}$ | $\begin{aligned} & \text { STP-MTR- } \\ & \text { 17060(D) } \end{aligned}$ | $\begin{aligned} & \text { STP-MTR- } \\ & \text { 23055(D) } \end{aligned}$ | $\begin{aligned} & \text { STP-MTR- } \\ & \text { 23079(D) } \end{aligned}$ | $\begin{aligned} & \text { STP-MTR- } \\ & \text { 34066(D) } \end{aligned}$ | $\begin{gathered} \text { STP- } \\ \text { MTRH- } \\ \text { 23079(D) } \end{gathered}$ | $\begin{gathered} \text { STP- } \\ \text { MTRH- } \\ 34066(D) \end{gathered}$ | $\begin{gathered} \text { STP- } \\ \text { MTRH- } \\ \text { 34097(D) } \end{gathered}$ | $\begin{gathered} \text { STP- } \\ \text { MTRH- } \\ 34127(D) \end{gathered}$ |
| NEMA Frame Size |  | 17 | 17 | 17 | 23 | 23 | 34 | 23 | 34 | 34 | 34 |
| * Maximum Holding Torque | (lb-in) | 3.81 | 5.19 | 7.19 | 10.37 | 17.25 | 27.12 | 17.87 | 27.12 | 50.00 | 80.50 |
|  | (oz-in) | 61 | 83 | 115 | 166 | 276 | 434 | 286 | 434 | 800 | 1288 |
|  | ( $\mathrm{N} \cdot \mathrm{m}$ ) | 0.43 | 0.59 | 0.81 | 1.17 | 1.95 | 3.06 | 2.02 | 3.06 | 5.65 | 9.12 |
| Rotor Inertia | (oz.in ${ }^{2}$ ) | 0.28 | 0.37 | 0.56 | 1.46 | 2.60 | 7.66 | 2.60 | 7.66 | 14.80 | 21.90 |
|  | $\left(\mathrm{kg} \cdot \mathrm{cm}^{2}\right)$ | 0.05 | 0.07 | 0.10 | 0.27 | 0.48 | 1.40 | 0.48 | 1.40 | 2.71 | 4.01 |
| Rated Current (A/phase) |  | 1.7 | 2.0 | 2.0 | 2.8 | 2.8 | 2.8 | 5.6 | 6.3 | 6.3 | 6.3 |
| Resistance (ת/phase) |  | 1.6 | 1.4 | 2.0 | 0.8 | 1.1 | 1.1 | 0.4 | 0.3 | 0.3 | 0.5 |
| Inductance (mH/phase) |  | 3.0 | 2.7 | 3.3 | 2.4 | 3.8 | 6.6 | 1.2 | 1.5 | 2.1 | 4.1 |
| Insulation Class |  | $130^{\circ} \mathrm{C}$ [266 ${ }^{\circ} \mathrm{F}$ ] Class B; 300V rms |  |  |  |  |  |  |  |  |  |
| Basic Step Angle |  | $1.8{ }^{\circ}$ |  |  |  |  |  |  |  |  |  |
| Shaft Runout (in) |  | 0.002 in [ 0.051 mm ] |  |  |  |  |  |  |  |  |  |
| Max Shaft Radial Play @ 1lb Ioad |  | 0.001 in [ 0.025 mm ] |  |  |  |  |  |  |  |  |  |
| Perpendicularity |  | 0.003 in [ 0.076 mm ] |  |  |  |  |  |  |  |  |  |
| Concentricity |  | 0.002 in [ 0.051 mm ] |  |  |  |  |  |  |  |  |  |
| * Maximum Radial Load (Ib [kg]) |  | 6.0 [2.7] |  |  | 15.0 [6.8] |  | 39.0 [17.7] | 15.0 [6.8] | 39.0 [17.7] |  |  |
| * Maximum Thrust Load (Ib [kg]) |  | 6.0 [2.7] |  |  | 13.0 [5.9] |  | 25.0 [11.3] | 13.0 [5.9] | 25.0 [11.3] |  |  |
| Storage Temperature Range |  | $-20^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}\left[-4^{\circ} \mathrm{F}\right.$ to $212^{\circ} \mathrm{F}$ ] |  |  |  |  |  |  |  |  |  |
| Operating Temperature Range |  | $-20^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}\left[-4^{\circ} \mathrm{F}\right.$ to $\left.122^{\circ} \mathrm{F}\right]$ (motor case temperature should be kept below $100^{\circ} \mathrm{C}\left[212^{\circ} \mathrm{F}\right]$ ) |  |  |  |  |  |  |  |  |  |
| Operating Humidity Range |  | 55\% to 85\% non-condensing |  |  |  |  |  |  |  |  |  |
| Product Material |  | steel motor case; stainless steel shatt(s) |  |  |  |  |  |  |  |  |  |
| Environmental Rating |  | IP40 |  |  |  |  |  |  |  |  |  |
| Weight (lb [kg]) |  | 0.6 [0.3] | 0.7 [0.3] | 0.9 [0.4] | 1.5 [0.7] | 2.2 [1.0] | 3.9 [1.7] | 2.4 [1.1] | 3.9 [1.7] | 5.9 [2.7] | 8.4 [3.8] |
| Agency Approvals |  | CE (complies with EN55014-1 (1993) and EN60034-1.5.11) |  |  |  |  |  |  |  |  |  |
| Design Tips |  | Allow sufficient time to accelerate the load and size the step motor with a $100 \%$ torque safety factor. <br> DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. <br> DO NOT connect or disconnect the step motor during operation. <br> Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation. <br> Use a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearings from minor misalignment. |  |  |  |  |  |  |  |  |  |
| Accessory Extension Cable |  | STP-EXT-020 |  |  |  |  |  | STP-EXTH-O2O |  |  |  |
| * For dual-shaft motors (STP-MTR-xxxxxD): <br> The sum of the front and rear Torque Loads, Radial Loads, and Thrust Loads must not exceed the applicable Torque, Radial, and Thrust load ratings of the motor. |  |  |  |  |  |  |  |  |  |  |  |

SureStep ${ }^{\circledR}$ Stepping Motors Mounting Accessory

| Mounting Aceessory - for NEWA 17 Surrestep Series Bipolar Stepping Motors |  |  |
| :---: | :---: | :---: |
| Part Number | Price | Description |
| STP-MTRA-RB-85 | 88.00 | Reducer bushing, 8 mm 0 D to 5 mm ID, 16 mm length, aluminum alloy <br> Connects NEMA size 17 stepper motors to Koyo TRD-NH and TRD-SH hollow shaft encoders. |

## Surestep ${ }^{\circ}$ Stepping System Motors



STP-MTR-17048(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)


STP-MTR-17060(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)
$\rightarrow$-70V Power Supply $-\bullet-48 \mathrm{~V}$ Power Supply $-\bullet-32 \mathrm{~V}$ Power Supply
Speed (rpm)


STP-MTR(H)-23xxx(D) NEMA 23 Step Motors

STP-MTR-23055(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)
—70V Power Supply --48 V Power Supply ---32 V Power Supply


STP-MTR-23079(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)
—70V Power Supply --48 V Power Supply --- 32V Power Supply
Speed (rpm)


STP-MTRH-23079(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)
—70V Power Supply --48 V Power Supply -- - 32V Power Supply


## Surestep. $^{\text {Stepping System Motors }}$

SureStep ${ }^{\circledR}$ Motor Torque vs. Speed Charts (continued)

## STP-MTR(H)-34xxx(D) NEMA 34 Step Motors

STP-MTR-34066(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)
—70V Power Supply - - 48V Power Supply --- 32V Power Supply
Speed (rpm)


STP-MTRH-34097(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping)

| -70 V Power Supply | --48 V Power Supply | ---32 V Power Supply |
| :---: | :---: | :---: |
| Speed (rpm) |  |  |



STP-MTRH-34066(D) Torque vs Speed ( $1.8^{\circ}$ motor; $1 / 2$ stepping)

| -70V Power Supply | - -48V Power Supply --- 32V Power Supply |
| :---: | :---: | :---: | Speed (rpm)



STP-MTRH-34127(D) Torque vs Speed ( $1.8^{\circ}$ step motor; $1 / 2$ stepping) -70V Power Supply $\quad-$-48V Power Supply --- 32V Power Supply

Speed (rpm)


## Surestep ${ }^{\circ}$ Stepping System Motors

## SureStep ${ }^{\circledR}$ Motor Dimensions and Cabling


${ }^{* *}$ Dimension $\mathrm{H}_{2}$ applies only to dual-shaft STP-xxxxxD motors.
${ }_{* *}$ Dimension D is the same for both front and rear shafts of dual-shaft motors.
** Dimensions J \& K do NOT apply to rear shafts of dual-shaft motors all rear shafts are round style).

| Surcstep Serics Dimensions \& Fabling - Fonnectorized Bjpolar Stepping Motors |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \text { Dimen } \\ \text {-sions* } \\ \text { (in } \left.[\mathrm{mm}]^{*}\right) \end{gathered}$ | High Torque Motors |  |  |  |  |  | Higher Torque Motors |  |  |  |
|  | $\begin{aligned} & \text { STP-MTR } \\ & \text {-17040(D) } \end{aligned}$ | $\begin{gathered} \text { STP-MTR } \\ -17048(D) \end{gathered}$ | $\begin{aligned} & \text { STP-MTR } \\ & \text {-17060(D) } \end{aligned}$ | $\begin{aligned} & \text { STP-MTR } \\ & -23055(\mathrm{D}) \end{aligned}$ | $\begin{aligned} & \text { STP-MTR } \\ & \text {-23079(D) } \end{aligned}$ | $\begin{aligned} & \text { STP-MTR } \\ & -34066(D) \end{aligned}$ | $\begin{aligned} & \text { STP-MTRH } \\ & -23079(D) \end{aligned}$ | $\begin{aligned} & \text { STP-MTRH } \\ & -34066(D) \end{aligned}$ | $\begin{aligned} & \text { STP-MTRH } \\ & -34097(D) \end{aligned}$ | $\begin{aligned} & \text { STP-MTRH } \\ & -34127(D) \end{aligned}$ |
| A | 1.67 [42.3] |  |  | 2.25 [57.2] |  | 3.39 [86.1] | 2.25 [57.2] | 3.39 [86.1] |  |  |
| B | 1.22 [31.0] |  |  | 1.86 [47.2] |  | 2.74 [69.6] | 1.86 [47.2] | 2.74 [69.6] |  |  |
| C | $\varnothing 0.87$ [22.1] |  |  | $\varnothing 1.50$ [38.1] |  | Ø 2.88 [73.0] | $\emptyset 1.50$ [38.1] | Ø 2.88 [73.0] |  |  |
| D** | 00.20 [5.0] |  |  | $\varnothing 0.25$ [6.4] |  | $\emptyset 0.50$ [12.7] | Ø 0.25 [6.4] | $\varnothing 0.50$ [12.7] |  |  |
| E | M3 x 0.5 thread 0.15 [3.8] min depth |  |  | $\text { Ø } 0.20 \text { [5.1] }$ <br> through |  | $00.26 \text { [6.6] }$ <br> through | $\text { Ø } 0.20 \text { [5.1] }$ through | $\varnothing 0.26 \text { [6.6] }$ <br> through |  |  |
| F | 1.58 [40.1] | 1.89 [48.0] | 2.34 [59.5] | 2.22 [56.4] | 3.10 [78.7] | 2.64 [67.1] | 3.10 [78.7] | 2.64 [67.1] | 3.82 [97.0] | 5.00 [127.0] |
| $\mathrm{H}_{1}$ | 0.94 [24.0] |  |  | 0.81 [20.6] |  | 1.46 [37.1] | 0.81 [20.6] | 1.46 [37.1] |  |  |
| $\mathrm{H}_{2}{ }^{\text {** }}$ | 0.39 [9.9] |  |  | 0.63 [16.0] |  | 1.13 [28.7] | 0.63 [16.0] | 1.13 [28.7] |  |  |
| J** | n/a |  |  | 0.59 [15.0] |  | 0.98 [25.0] | 0.59 [15.0] | 0.98 [25.0] |  |  |
| K** | n/a |  |  | 0.23 [5.8] |  | 0.45 [11.4] | 0.23 [5.8] | 0.45 [11.4] |  |  |
| L | 12.0 [305] |  |  |  |  |  | 12 [305] |  |  |  |
| Conductor | (4) \#20 AWG |  |  |  |  |  | (4) \#18 AWG |  |  |  |
| Connector | Molex \# 43025-0400 |  |  |  |  |  | Molex \# 39-01-3042 |  |  |  |
| Pin | Molex \# 43030-0007 |  |  |  |  |  | Molex \# 39-00-0039 |  |  |  |
| * mm dimensions are for reference purposes only. <br> ** Dimension $\mathrm{H}_{2}$ applies only to dual-shaft STP-xxxxxD motors. <br> Dimension D (shaft diameter) is the same for both front and rear shafts of dual-shaft motors. Dimensions J \& K do NOT apply to rear shafts of dual-shaft motors (all rear shafts are round style). |  |  |  |  |  |  |  |  |  |  |

## Surestep ${ }^{\circ}$ Stepping System Cables

## SureStep ${ }^{\circledR}$ Cables

| SureStep Series - Stepping System Fables |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Cable | Price | Purpose | Length | Use With | Cable End Connectors |
| STP-EXT-020 | \$15.00 | motor to drive extension | 20 ft | STP-MTR-xxxxx(D) | pigtail / Molex 43020-0401 connector |
| STP-EXTH-020 | \$30.00 | motor to drive extension | 20 ft | STP-MTRH-xxxxx(D) | pigtail / Molex 39-01-2041 connector |
| STP-232RJ11-CBL * | \$9.00 | programming/communication | 10 ft | $\begin{aligned} & \text { STP-DRV-4850 } \\ & \hline \end{aligned}$ | DB9 female / RJ11(6P4C) |
| STP-232HD15-CBL-2 ** | \$10.00 | communication | 6.6 ft | $\begin{aligned} & \text { STP-DRV-4850 } \\ & \hline \end{aligned}$ | HD 15-pin male / RJ12 6-pin plug |
| STP-232RJ12-CBL-2 ** | \$5.50 | communication | 6.6 ft | $\begin{aligned} & \text { STP-DRV-4850 } \\ & \hline \end{aligned}$ | RJ12 6-pin plug / RJ12 6-pin plug |
| * Programming/communication cable STP-232RJ11-CBLis available for spare or replacement purposes. <br> (One cable is included with each software programmable drive.) <br> ** Refer to the ZIPLinks Wiring Solutions section for complete information regarding cables STP-232HD15-CBL-2 and STP-232RJ12-CBL-2. |  |  |  |  |  |

## Extension Cable Wiring Diagram



## Programming Cable Wiring Diagram



SureStep ${ }^{\circledR}$ Power Supplies

| SureStep Series Specifioations - Stepping System Power Supplies |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Power Supply | STP-PWR-3204 | STP-PWR-4805 | STP-PWR-4810 | STP-PWR-7005 |
| Price | \$120.00 | \$140.00 | \$178.00 | \$178.00 |
| Input Power (fuse protected *) | 1-phase, 120/240 VAC, $50 / 60 \mathrm{~Hz}$, <br> 150 VA <br> Fuse*: 3A | 1-phase, 120/240 VAC, $50 / 60 \mathrm{~Hz}$, $350 \text { VA }$ Fuse*: 5A | 1-phase, 120/240 VAC, $50 / 60 \mathrm{~Hz}$, 650 VA Fuse*: 8A | 1-phase, 120/240 VAC, $50 / 60 \mathrm{~Hz}$, $500 \text { VA }$ Fuse*: 7A |
| Input Voltage Range (switch selectable) | 120/240 VAC $\pm 10 \%$ (Voltage range switch is set to 240 VAC from factory) |  |  |  |
| Inrush Current | 120 VAC < $12 \mathrm{~A} / 240 \mathrm{VAC}$ < 14 A | 120 VAC <20A / 240 VAC < 24A | 120 VAC < 40A / 240 VAC < 50A |  |
| Motor Supply Output (linear unregulated, fuse protected *, and power on LED indicator) | 32 VDC @ 4A (fully loaded) 35 VDC @ 1A load 41 VDC @ no load Fuse*: 6A <br> (Electrically isolated from Logic Supply Output) | 46.5 VDC @ 5 A (fully loaded) 52 VDC @ 1A load 57.5 VDC @ no load Fuse*: 8A | 46.5 VDC @ 10A (tully loaded) 50 VDC @ 1 A load 57.5 VDC @ no load Fuse*: 15A | 70 VDC @ 5 A (fully loaded) 79 VDC @ 1A load 86.5 VDC @ no load Fuse*: 8A |
| Logic Supply Output (regulated and power on LED indicator) | $5 \mathrm{VDC} \pm 5 \% @ 500 \mathrm{~mA}$(Electronically Overload Protected)(Electrically isolated from Motor Supply Output) |  |  |  |
| Watt Loss | 13W | 25W | 51W | 42W |
| Storage Temperature Range | -55 to $85^{\circ} \mathrm{C}$ [-67 to $\left.185{ }^{\circ} \mathrm{F}\right]$ |  |  |  |
| Operating Temperature Range | 0 to $50^{\circ} \mathrm{C}$ [ 32 to $122{ }^{\circ} \mathrm{F}$ ] full rated; derate current $1.1 \%$ per degree above $50^{\circ} \mathrm{C}$; $70^{\circ} \mathrm{C}\left[158{ }^{\circ} \mathrm{F}\right]$ maximum |  |  |  |
| Humidity | $95 \%$ (non-condensing) relative humidity maximum |  |  |  |
| Cooling Method | Natural convection (mount power supply to metal surface if possible) |  |  |  |
| Dimensions (in [mm]) | $\begin{gathered} 4.00 \times 7.00 \times 3.25 \\ {[101.6 \times 177.8 \times 82.6]} \end{gathered}$ | $\begin{gathered} 5.00 \times 8.10 \times 3.88 \\ {[127.0 \times 205.7 \times 98.6]} \end{gathered}$ | $\begin{gathered} 5.62 \times 9.00 \times 4.62 \\ {[142.7 \times 228.6 \times 117.3]} \end{gathered}$ |  |
| Mounting | Mount on either wide or narrow side with machine screws per dimension diagrams |  |  |  |
| Weight (lb [kg]) | 6.5 [2.9] | 11 [4.9] | 18 [8.3] | 16 [7.2] |
| Connections | Screw Terminals |  |  |  |
| Agency Approvals | UL (file \# E181899), CSA, CE |  |  |  |
| ${ }^{*}$ Fuses to be replaced by qualified service personnel only. Use (1-1/4 $\times 1 / 4$ in) ceramic fast-acting fuses (Edison type ABC from AutomationDirect, or equivalent). |  |  |  |  |

Power Supply Dimensions


## Surestep $_{\text {step }}$ Stepping System Power Supplies

SureStep ${ }^{\circledR}$ Power Supply Dimensions (continued)

## STP-PWR-4805, -4810, -7005 Power Supplies



Surestep Series Dimensions - 48V \& 70V Power Supplies

| Power Supply Part Number | Dimensions* (in [mm]*) |  |  |  |  |  |  |  |  |  |  | Mtg Screw |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | B | C | D | E | F | G | H | J | K | L |  |
| STP-PWR-4805 | 8.10 [205.7] | 3.88 [98.6] | 5.00 [127.0] | 0.87 [22.1] | 4.67 [118.6] | 0.25 [6.4] | 7.15 [181.6] | 7.75 [196.9] | 0.50 [12.7] | 3.53 [89.7] | 0.200 [5.1] | \#10 |
| $\begin{array}{\|l\|l\|} \hline \text { STP-PWR-4810 } \\ \hline \text { STP-PWR-7005 } \end{array}$ | 9.00 [228.6] | 4.62 [117.3] | 5.62 [142.7] | 1.56 [39.6] | 4.06 [103.1] | 0.35 [8.9] | n/a | 8.59 [218.2] | 0.50 [12.7] | 4.27 [108.5] | 9/32 [7.1] | 1/4 |

* mm dimensions are for reference purposes only.


## Surestepastepping Systems with PLCs

## Controller Compatibility

| Motion Pontrol with Automation Ifrect PL.Bs* and Surcstep Stepping Systems |  |  |  |
| :---: | :---: | :---: | :---: |
| PLC Series | Starting at \$198.00 | Starting at \$125.00 | Starting at \$251.00 |
|  | 1 axis control** | 1-2 axis control*** | 1-5 axis contro\|*** |
|  | DL105 | DL05* | DL06* |
|  |  |  |  |
| Built-In PLC Pulse Outputs | 1 axis pulse output included with the PLC base unit. |  |  |
| Maximum Pulse Rate Output | 7,000 pulses/sec |  | 10,000 pulses/sec |
| Target Pulse Range | $-8,388,608$ to $+8,388,607$ pulses |  |  |
| Minimum Velocity | 40 pulses/sec |  |  |
| Velocity Resolution | 10 pulses/sec |  |  |
| Accel/Decel Range | 0.1 to 10 sec |  |  |
| Position Control | Trapezoidal Profiles |  |  |
| Velocity Control | Velocity Levels |  |  |
|  |  |  |  |
| I/O Modules Pulse Outputs | Not Applicable for DL105 | H0-CTRIO (1 axis per module) |  |
| Maximum Pulse Rate Output |  | 25,000 pulses/sec |  |
| Target Pulse Range |  | + / - 2.1 billion pulses (31 bits plus sign) |  |
| Minimum Velocity |  | 40 pulses/sec |  |
| Velocity Resolution |  | 10 pulses/sec |  |
| Accel/Decel Range |  | 0.1 to 10 sec |  |
| Position Control |  | Trapezoidal Profiles (linear \& S-curve ramps) |  |
| Velocity Control |  | Dynamic Velocity (controlled accel/decel) |  |
| Maximum Number of Modules |  | 1 | 4 |
| * Any AutomationDirect PLC capable of RS-232 ASCII communication can write serial commands to the SureStep Advanced Microstepping Drives (STP-DRV-4850 \& 80100). These PLCs include DirectLOGIC series DL 05, 06, 250-1, 260, 350, \& 450, as well as CLICK, Do-more and P3000 series. However, we strongly recommend using DL06, DL260, Do-more, CLICK, or Productivity 3000 PLCs for serial commands due to their more advanced ASCII instruction set which includes PRINTV and VPRINT commands. |  |  |  |
| ** When using DC output models only. *** When using either DC output model or HO-CTRIO option module. |  |  |  |

* Any AutomationDirect PLC capable of RS-232 ASCII communication can write serial commands to the SureStep Advanced Microstepping Drives (STP-DRV-4850 \& 80100). These PLCs include DirectLOGIC series DL 05, 06, 250-1, 260, 350, \& 450, as well as CLICK, Do-more and P3000 series. However, we strongly recommend using DL06, DL260, Do-more, CLICK, or Productivity 3000 PLCs for serial commands due to their more advanced ASCII instruction set which includes PRINTV and VPRINT commands. ** Using D2-CTRINT or Hx-CTRIO modules.


## Surestep ${ }^{\text {stepping }}$ Systems with PLCs

Controller Compatibility (continued)

| Motion Control with PC-based Control and SureStepe Stepping Systems |  |  |  |
| :---: | :---: | :---: | :---: |
| 1-16 axis control depending on base size and power supply budget * |  |  |  |
| Controller Series | PC-based motion control with Think \& Do on your Windows PC or our embedded WinPLC |  |  |
| I/O Modules Pulse Outputs | (2 axes per module) | $\frac{\text { T1H-CTRIO }}{(2 \text { axes per module) }}$ | $\frac{\text { H2-CTRIO2 }}{(2 \text { axes })}$ |
| Maximum Pulse Rate Output | 25,000 pulses/sec | 25,000 pulses/sec | 250,000 pulses/sec |
| Target Pulse Range | +/-2.1 billion pulses |  |  |
| Minimum Velocity | 25 pulses/sec |  |  |
| Velocity Resolution | 1 pulse/sec |  |  |
| Accel/Decel Range | 0.1 to 10 sec |  |  |
| Position Control | Trapezoidal Profiles (linear and S-curve ramps) |  |  |
| Velocity Control | Dynamic Velocity (controlled accel/decel) |  |  |
| Maximum Number of Modules | 1-8 |  |  |
| * Using Hx-CTRIO modules |  |  |  |

## NEMA Planetary Gearboxes

The SureGear PGCN series easily mates to SureStep motors, and other NEMA frame motors.
Everything you need to mount your SureStep motor is included!
It is the perfect solution for applications such as material
handling, pick and place, automation, packaging, and
other motion control applications requiring a NEMA
input/output interface. available in NEMA 17, 23 and 34 frame sizes

# Precision Gearboxes for Stepper Motors 

## Sure

Tough on the outside, precision quality on the inside


# Suregear <br> <br> Planetary Gearboxes for NEMA Motors 

 <br> <br> Planetary Gearboxes for NEMA Motors}

## SureGear ${ }^{\circledR}$ Planetary Gear Reducers for NEMA Motors - Overview

The SureGear PGCN series is a great gearbox (gear reducer) value for servo, stepper, and other motion control applications requiring a NEMA size input/output interface. It offers the best quality available for the price point.

## Features

-Wide range of ratios ( $5,10,25,50$, and $100: 1$ )

- Low backlash of 30 arc-min or less
- 20,000 hour service life
- Maintenance free; requires no additional lubrication
- NEMA sizes 17,23 , and 34
- Includes hardware for mounting to SureStep stepper motors
- Optional shaft bushings available for mounting to other motors


Applications

- Pick and place
- Automation
- Packaging
- Other motion control applications requiring a NEMA input/output

| Surchear ${ }^{\text {® }}$ NEMA Planctary Mearboxes |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Model-Specific Specifications |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Part Number | Price | 읒 |  |  |  |  |  |  |  |  |  | - 른 른 |  | Fits SureStep Stepper Motor |
| PGCN17-055M | \$209.00 | 5:1 |  | 6.5 [58] | 13 [115] | 26 [230] | <25 |  |  | 0.8 [7.5] | 0.0096 [0.003] | 94 | 0.45 [1.0] |  |
| PGCN17-105M | \$214.00 | 10:1 |  | 5.0 [44] | 10 [89] | 20 [177] | $<25$ |  |  | 0.5 [4.4] | 0.0078 [0.003] | 94 | 0.45 [1.0] |  |
| PGCN17-255M | \$267.00 | 25:1 | 17 | 16 [142] | 20 [177] | 32 [283] | $<30$ |  |  | 0.8 [7.5] | 0.0096 [0.003] | 92 | 0.55 [1.2] | STP-MTR-170xx(D) |
| PGCN17-505M | \$267.00 | 50:1 |  | 16 [142] | 20 [177] | 32 [283] | $<30$ |  |  | 0.8 [7.5] | 0.0078 [0.003] | 92 | 0.55 [1.2] |  |
| PGCN17-1005M | \$267.00 | 100:1 |  | 5.0 [44] | 10 [89] | 20 [177] | $<30$ |  |  | 0.5 [4.4] | 0.0078 [0.003] | 92 | 0.55 [1.2] |  |
| PGCN23-0525 | \$285.00 | 5:1 |  | 6.5 [58] | 13 [115] | 26 [230] | $<20$ | 361 [81] | 298 [67] | 0.9 [8.0] |  | 94 | 0.45 [1.0] |  |
| PGCN23-1025 | \$285.00 | 10:1 |  | 5.0 [44] | 10 [89] | 20 [177] | $<20$ |  |  | 0.6 [5.3] |  | 94 | 0.45 [1.0] |  |
| PGCN23-2525 | \$310.00 | 25:1 | 23 | 16 [142] | 20 [177] | 32 [283] | <25 |  |  | 0.9 [8.0] | 0.04 [0.014] | 92 | 0.55 [1.2] | STP-MTR(H)-230xx(D) |
| PGCN23-5025 | \$310.00 | 50:1 |  | 16 [142] | 20 [177] | 32 [283] | $<25$ |  |  | 0.9 [8.0] |  | 92 | 0.55 [1.2] |  |
| PGCN23-10025 | \$310.00 | 100:1 |  | 5.0 [44] | 10 [89] | 20 [177] | $<25$ |  |  | 0.6 [5.3] |  | 92 | 0.55 [1.2] |  |
| PGCN34-0550 | \$335.00 | $5: 1$ |  | 26 [230] | 44 [389] | 84 [743] | $<15$ |  |  | 2.4 [21.2] | 0.36 [0.123] | 94 | 1.1 [2.4] |  |
| PGCN34-1050 | \$335.00 | 10:1 |  | 16 [142] | 24 [212] | 62 [549] | <15 |  |  | 1.3 [11.5] | 0.34 [0.116] | 94 | 1.1 [2.4] |  |
| PGCN34-2550 | \$394.00 | 25:1 | 34 | 42 [372] | 52 [460] | 84 [743] | <20 | 476 [107] | 425 [96] | 2.4 [21.2] | 0.36 [0.123] | 92 | 1.4 [3.1] | STP-MTR(H)-34xxx(D) |
| PGCN34-5050 | \$394.00 | 50:1 |  | 42 [372] | 52 [460] | 84 [743] | $<20$ |  |  | 2.4 [21.2] | 0.34 [0.116] | 92 | 1.4 [3.1] |  |
| PGCN34-10050 | \$394.00 | 100:1 |  | 16 [142] | 24 [212] | 62 [549] | $<20$ |  |  | 1.3 [11.5] | 0.34 [0.116] | 92 | 1.4 [3.1] |  |
| Specifications Applicable to AII PGCN Gearboxes |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Nominal Speed (rpm) |  |  | 3500 |  |  |  |  |  |  |  |  |  |  |  |
| Maximum Input Speed (rpm) |  |  | 6000 |  |  |  |  |  |  |  |  |  |  |  |
| Mounting Orientation |  |  | can be mounted in any orientation |  |  |  |  |  |  |  |  |  |  |  |
| Environmental Rating |  |  | IP64 |  |  |  |  |  |  |  |  |  |  |  |
| Operating Temperature |  |  | -20 to $90{ }^{\circ} \mathrm{C}$ [-4 to $194{ }^{\circ} \mathrm{F}$ ] |  |  |  |  |  |  |  |  |  |  |  |
| Lubrication |  |  | Mineral Grease EPO |  |  |  |  |  |  |  |  |  |  |  |
| Service Life (hrs) |  |  | >20,000 |  |  |  |  |  |  |  |  |  |  |  |
| NOTE: SureGear PGCN gearboxes (gear reducers) are not designed for back driving. |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

## Sureagear Planetary Gearboxes for NEMA Motors

Dimensions (dimensions $=\mathrm{mm}[\mathrm{in}]$ )


PGCN23-xxxx SureGear Dimension Drawing


PGCN34-xxxx SureGear Dimension Drawing

| Surchear ${ }^{\text {® }}$ NEMA Planctary Gearhox Dimensions ( dimensions = mm [in] ) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| NEMA-17 Part Number | PGCN17-055M | PGCN17-105M | PGCN17-255M | PGCN17-505M | PGCN17-1005M |
| dimension A | 84.0 [3.31] |  | 99.8 [3.93] |  |  |
| dimension B | 109.4 [4.31] |  | 125.2 [4.93] |  |  |
| NEMA-23 Part Number | PGCN23-0525 | PGCN23-1025 | PGCN23-2525 | PGCN23-5025 | PGCN23-10025 |
| dimension A | 77.6 [3.06] |  | 95.2 [3.75] |  |  |
| dimension B | 103.0 [4.06] |  | 120.6 [4.75] |  |  |
| NEMA-34 Part Number | PGCN34-0550 | PGCN34-1050 | PGCN34-2550 | PGCN34-5050 | PGCN34-10050 |
| dimension A | 99.3 [3.91] |  | 121.3 [4.78] |  |  |
| dimension B | 131.1 [5.16] |  | 153.0 [6.02] |  |  |



Typical PGCN Accessory Bushings


Typical PGCN Accessory Screws

| Surchear ${ }^{(8)}$ NEMA Planctary Gearbox Accessories |  |  |  |
| :---: | :---: | :---: | :---: |
| Part Number | Price | Description | Fits SureGear NEMA Planetary Gearbox |
| PGCN17-SK | \$3.00 | Mounting screws, replacement, for SureGear NEMA size 17 gearboxes (Package of 4) |  |
| PGCN17-BSH5M | \$6.00 | Motor shaft bushing for SureGear NEMA size 17 gearboxes, fits 5 mm diameter motor shaft |  |
| PGCN17-BSH8M | \$6.00 | Motor shaft bushing for SureGear NEMA size 17 gearboxes, its 8mm diameter motor shatt | PGCN17-xxxx |
| PGCN17-BSH9M | \$6.00 | Motor shaft bushing for SureGear NEMA size 17 gearboxes, fits 9 mm diameter motor shaft |  |
| PGCN17-BSH25 | \$6.00 | Motor shaft bushing for SureGear NEMA size 17 gearboxes, fits $1 / 4$ inch diameter motor shaft |  |
| PGCN23-SK | \$3.00 | Mounting screws, replacement, for SureGear NEMA size 23 gearboxes (Package of 4) |  |
| PGCN23-BSH8M | \$6.00 | Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits 8 mm diameter motor shaft |  |
| PGCN23-BSH9M | \$6.00 | Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits 9mm diameter motor shaft | PGCN23-xxxx |
| PGCN23-BSH25 | \$6.00 | Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits $1 / 4$ inch diameter motor shaft |  |
| PGCN23-BSH37 | \$6.00 | Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits $3 / 8$ inch diameter motor shaft |  |
| PGCN34-SK | \$3.00 | Mounting screws, replacement, for SureGear NEMA size 34 gearboxes (Package of 4) |  |
| PGCN34-BSH9M | \$6.00 | Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits 9 mm diameter motor shaft |  |
| PGCN34-BSH11M | \$6.00 | Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits 11 mm diameter motor shaft | PGCN34-xxxx |
| PGCN34-BSH37 | \$6.00 | Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits $3 / 8$ inch diameter motor shaft |  |
| PGCN34-BSH50 | \$6.00 | Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits $1 / 2$ inch diameter motor shaft |  |

## Sure servo $_{\text {AC }}$

## SureServo ${ }^{\circledR}$ AC servo systems

The SureServo family of brushless servo systems from AutomationDirect is fully digital and offers a rich set of features at dynamite prices. Choose from eight standard servo motors that are used in combination with one of three standard servo drives.

- Eight standard systems from 100 W to 3 kW
- Use with AutomationDirect CLICK,

DirectLOGIC, or P3000 PLCs; or any other host controller

- Drives feature on-board indexer and adaptive tuning modes
- Free setup software
-30-day money-back ģuarantee
- Two year warranty


## Why use a servo?

The SureServo servo systems provide the highest possible level of performance for precise control of position, velocity, and torque. Compared to lower cost stepping systems, the SureServo products provide:

- More torque at higher speeds (up to $5,000 \mathrm{rpm}$ )
- Broader range of power (up to 3 kW )
- Higher response with closed-loop control
(high hit rate without stalling or lost position)



## SureServo family

The SureServo family is designed for flexibility and quick implementation. SureServo drives accept a wide range of command sources:

- Built-in motion controller w/preset
position, velocity or torque
- Select presets with switch inputs and/or the multi-drop Modbus serial interface
- Position commands with "pulse and direction" or "count up and down" format
- Analog voltage Velocity or Torque command
- Encoder follower

CHECK OUT OUR PRICES


Complete 1.xist oow syitem $\$ 986.00$
\$2,284.20
All prices are U.S. list prices, AutomationDirect prices are from April 2014 Price List. The Allen-Bradley
100 W system consists of part numbers shown in table above with prices from 100 W system consists of part numbers shown in table above with prices from
www.rockwellautomation.com/en/e-tools $2 / 20 / 2014$.

For configuration, tuning and diagnostics, use the drive's integrated keypad /display or take advantage of the free SureServo Pro ${ }^{\oplus}$ PC-based software. Tune the system easily with adaptive auto-tuning selections or a manual mode.
Adapt to diverse applications with configurable I/O, including eight digital inputs, five digital outputs, two analog monitors and a scalable encoder output.

## Sure servo AC Servo Systems

# 3 Standard Drives ... 8 Standard Motors ... 100W to 3kW ... plus 25 gearboxes with four ratios 



## Drive features

- Main Power and Control Power Inputs
- Main Power: 230 VAC 1-phase/3-phase ( 2 kW and 3 kW systems are 3 -phase only)
- Control Power: 230 VAC Single Phase; $50 / 60 \mathrm{~Hz}$
- Fully digital with up to 450 Hz velocity loop response
- Easy setup and diagnostics with built-in keypad/display or the SureServo Pro PC-based software
- Five-in-one command options include:
- $\pm 10 \mathrm{~V}$ torque or velocity command
- Pulse train or master encoder position command (accepts line driver or open collector) with electronic gearing
- Built-in indexer for position control using 8 preset positions and/or position setpoint with serial Modbus
- Tuning aids include inertia estimation and easy tuning for up to 10 levels of response
- Optically isolated digital inputs (8) and outputs (5), analog outputs for monitor signals (2), and line driver output for encoder (with scalable resolution)


## SureServo <br> tuning technology

The SureServo drive closes the loop on current, velocity, and position (depending on control mode selection). Proportional gain, integral gain, feed forward compensation, command low pass filter, and a notch filter for resonance suppression are available. There are three tuning modes:

1. "Manual Mode" for user-defined adjustments
2. "Easy Mode" for default settings over a wide range of programmed inertia with 10 response levels
3. "Auto Mode" for automatic adjustment using an estimated (or measured) value of inertia

## SureServo built-in motion controller

While the SureServo drives can accept traditional commands from host controls, they can also provide their own internal motion control. For example, up to eight index moves can be pre-defined and stored in the drive and then selected and executed using up to three discrete inputs. The predefined index profiles can also be changed via serial communications. The motion can be incremental or absolute (homing routines are available in the drive) and acceleration can be linear or S-curve.
Multiple drives can be daisy-chained and addressed separately using the drive's serial port. This allows very simple yet powerful control of multi-axis processes that do not need precise path control but only precise starting and stopping points. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion.

## SureServo Optional Holding Brake

Each SureServo motor can be ordered with an optional 24 VDC spring-set holding brake that holds the motor in place when power is removed.

## SureGear ${ }^{\circledR}$ Precision Gearboxes for <br> Servo motors

## Inertia balancing issue in your design?

The SureGear PGA series easily mates to SureServo motors. Everything you need to mount your SureServo motor is included!

- Four ģear ratios available ( $5,10,15,25: 1$ )
- Mounting hardware included for attaching to SureServo motors
- Industry-standard mounting dimensions
- Thread-in mounting style
- Best-in-class backlash (5 arc-min)
- 5-year warranty


## Sureservo AC Servo Systems

Traditional Command Sources


## Sure $\underset{\text { servo }}{\text { AC Servo Systems }}$

## How to select and apply <br> SureServo systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque SureServo system that most closely matches these parameters for


## 1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the servo system.
In general, applications that need high response or bandwidth will
the system being replaced. In a new application, these parameters should be determined through calculation and/or measurement.
AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizerSureServo" software can be downloaded from www.sureservo.com/downloads.htm.
Information for selecting SureServo systems is also included in Appendix B of the SureServo User Manual, which can be downloaded from the AutomationDirect.com website.

## 2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torquespeed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed).
benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. Systems with ratios as high as 200:1 can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. SureServo systems may be tuned manually, adaptively with measurement of the load inertia, or set with default tuning based on a programmed value of load inertia.


## Sure servo $_{\text {AC Servo Systems }}$

## Application tip - <br> coupling considerations

The SureServo motors have keyless shafts that are designed for use with clamp-on or compression style couplings. Couplings using keys and/or set screws should NOT be used with SureServo motors as they are likely to come loose or damage the motor shaft. "Servo-grade" clamp-on or compression style couplings are usually the best choice when you consider the
stiffness, torque rating, and inertia. Higher stiffness (lb-in/radian) is needed for better response but there is a trade-off between the stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the SureServo peak torque requirement of your application.

## Coupling Suppliers: www.sureservo.com/couplingconsiderations.htm

## Mechanical transmissions

Common mechanical transmissions include leadscrews, rack \& pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack \& pinion, or conveyor are common ways to
translate the rotary motion of the servo motor into linear motion of the load. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

## 1. Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. SureServo systems can go up to $5,000 \mathrm{rpm}$ for the low inertia motors and up to 3,000 rpm for the medium inertia motors.
Example: A gearbox reduces the required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to $1 / 10$, increases output torque 10 times, and decreases reflected inertia to $1 / 100$.
However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

## 2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

## 3. Space limitations and motor orientation

SureServo motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned. For example, some reducers would allow for in-line, right angle, or parallel mounting of the motor.
For more information, refer to the website listed below.

## Ordering guide instructions

The following four pages are your ordering guide for the eight standard SureServo systems. Each of the eight standard systems has a torque-speed curve including the motor inertia for reference. This is the fundamental information that you need to select the servo drive and matching motor for your application.

## Don't forget the cables and ZIPLink break-out board kit!

Included in the ordering guide are the available connection cables from the drive to motor in standard lengths from 10 to 60 feet. The break-out board kit includes a 0.5 m ( 19 inch) cable for the CN1 I/O interface, and is listed for your convenience. We highly recommend all five items per system as a minimum. All cables are $100 \%$ factory tested to make your system installation as easy and quick as possible. See the Accessories section for regeneration resistors, AC line filters, fuses, contactors, and RF noise filters.

## Sureservo AC Servo System Configuration

SureServo series drives and motors part numbering system


2：230VAC； $50 / 60 \mathrm{~Hz}$
Here is what you will need to order a complete servo system：


NOTE：UNIT CAN BE PROGRAMMED VIA KEYPAD． Optional programming software（free download）and optional programming cable available．


If you need a gear box for your configuration，you can do it easily online：
http：／／www．sureservo．com／gearbox／selector
SureServo AC servo drive，motor，and cable combinations

|  | ertia Power | Drive and Motor |  |  | Power Cables（from Drive to Motor） |  |  |  | Encoder Feedhack Gables |  |  |  | Miscellaneous |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| － | む̀ む̀ | ® 0.3 0 0 0 | Servo Motor without brake （note） | Servo Motor with brake （note） | 10 ft | 20 ft | 30 ft | 60 ft | 10 ft | 20 ft | 30 ft | 60 ft | ZIPLink I／O <br> Interface | RS－422／485 <br> Serial Com－ <br> munication <br> Cable |
|  | 100W | $\begin{aligned} & \stackrel{i}{0} \\ & \stackrel{1}{4} \\ & \stackrel{1}{00} \end{aligned}$ | SVL－201 | SVL－201B | SVC－ PFL－010 | SVC－ PFL－020 | SVC－ PFL－030 | $\begin{array}{\|l\|l\|} \text { SVC- } \\ \text { PFL-0. } \end{array}$ | SVC－ EFL－010 | $\left\lvert\, \begin{aligned} & \text { SVC- } \\ & \text { EFL-020 } \end{aligned}\right.$ | SVC－ EFL－030 | SVC－ EFL－060 |  |  |
|  | 200W |  | SVL－202 <br> SVL－204 | SVL－202B <br> SVL－204B |  |  |  |  |  |  |  |  | $\frac{\text { ZL-RTB50 }}{\text { and }}$ |  |
|  | 750W | $\begin{aligned} & \text { on } \\ & \text { N } \\ & \text { y } \\ & \text { in } \end{aligned}$ | SVL－207 | SVL－207B |  |  |  |  |  |  |  |  | ZL－SVC－CBL50 | SVC－MDCOM－CBL |
|  | 1000W |  | SVL－210 <br> SVM－210 | SVL－210B <br> SVM－210B | SVC－ PHM－010 | SVC－ PHM－O2O | SVC－ <br> PHM－030 | SVC－ <br> PHM－060 | SVC－ EHH－010 | SVC－ EHH－020 | SVC－ EHH－030 | SVC－ EHH－060 | $\begin{aligned} & \overline{o r} \\ & \text { ZL-SVC-CBL50-1 } \\ & \text { ZLL-SVC-CBL50-2 } \end{aligned}$ |  |
| $\stackrel{\text { 亳 }}{\text { ¢ }}$ | 2000W |  | SVM－220 <br> SVM－230 | SVM－220B <br> SVM－230B | SVC－ PHH－010 | SVC－ PHH－02O | SVC－ <br> PHH－030 | $\left\lvert\, \begin{aligned} & \text { SVC- } \\ & \text { PHH-060 } \end{aligned}\right.$ |  |  |  |  |  |  |
| Note：EACH SERVO MOTOR REQUIRES AN ENCODER FEEDBACK CABLE AND A POWER CABLE． <br> The motor power cable includes brake power wires for the optional motor brake． |  | Note：EACH SERVO MOTOR REQUIRES AN ENCODER FEEDBACK CABLE AND A POWER CABLE． <br> THE MOTOR POWER CABLE INCLUDES BRAKE POWER WIRES FOR THE OPTIONAL MOTOR BRAKE． |  |  |  |  |  |  |  |  |  |  |  |  |

## Surevervo AC Servo System Configuration

For all systems:

100W Low Inertia System

$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=\mathbf{0 . 0 0 0 0 2 7 \mathrm { Ib } - \mathrm { in } - \mathbf { s } ^ { \mathbf { 2 } } ( \mathbf { 0 . 0 0 0 0 0 3 } \mathbf { ~ k g } - \mathrm { m } ^ { 2 } )}$

Order programming software 8 programming cable if needed See pgs. MC-35 \& MC-36.


Servo Drive
SVA-2040 \$488.00

## 200W Low Inertia System


$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=\mathbf{0 . 0 0 0 1 6 \mathrm { lb } - \mathrm { in } - \mathrm { s } ^ { 2 } ( \mathbf { 0 } . 0 0 0 0 1 8 \mathrm { kg } - \mathrm { m } ^ { 2 } )}$

SureServo Motor


Motor Power Cable (1)



Motor Encoder Cable (1)


SVC-EFL-010 (10') $\$ 49.50$
SVC-EFL-020 (20') \$73.00
SVC-EFL-030 ( $30^{\prime}$ ) $\quad \$ 87.00$
SVC-EFL-060 ( $60^{\prime}$ ) $\$ 113.00$


## 400W Low Inertia System



400W Low Inertia

SureServo Motor


Motor Encoder Cable (1)


|  |  |
| :--- | :--- |
| SVC-EFL-010 | $\left(10^{\prime}\right)$ |
| SVC-EFL-020 | $\$ 49.50$ |
| (20) | $\$ 73.00$ |
| SVC-EFL-030 | $\left(30^{\prime}\right)$ |
| SVC-EFL-060 | (60') |



ZIPLink V/O Interface

$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=\mathbf{0} .0003 \mathrm{lb}-\mathrm{in}-\mathrm{s}^{2}\left(\mathbf{0} .000034 \mathrm{~kg}-\mathrm{m}^{2}\right)$

## Sure servo AC Servo System Configuration

For all systems:
Order programming software \&

750W Low Inertia System

$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=.00096 \mathrm{Ib}-\mathrm{in}-\mathrm{s}^{2}\left(\mathbf{0 . 0 0 0 1 0 8} \mathbf{~ k g ~ - ~} \mathrm{~m}^{2}\right)$


Motor Power Cable (1)

|  |  |
| :--- | :--- |
| 3. |  |
| SVC-PFL-010 | $\left(10^{\prime}\right)$ |
| SVC-PL-020 | (20) |
| SVC-PFL-030 | (30.50 |
| SVC-PFL-060 | ( $\left.60^{\prime}\right)$ |

## Motor Encoder Cable (1)



## ZIPLink VO Interface

1 kW Low Inertia System

$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=.0023 \mathrm{lb}-\mathrm{in}-\mathrm{s}^{2}\left(0.00026 \mathrm{~kg}-\mathrm{m}^{2}\right)$


Motor Power Cable (1)



## Sure servo AC Servo System Configuration <br> For all systems:

2 kW Medium Inertia System

| Torque |
| :--- |
| (N-m) |

Order programming software \& programming cable if needed. See pgs. MC-35\& MC-36.

$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=.014 \mathrm{lb}-\mathrm{in}-\mathrm{s}^{2}=\left(0.00158 \mathrm{~kg}-\mathrm{m}^{2}\right)$


$\mathrm{J}_{\mathrm{m}}=$ Motor Inertia $=\mathbf{0 . 0 3 8} \mathrm{Ib}-\mathrm{in}-\mathrm{s}^{2}=\left(\mathbf{0 . 0 0 4 3 3} \mathbf{k g}-\mathrm{m}^{2}\right)$

3 kW Medium Inertia System


3 kW Medium Inertia



## Sure servo AC Servo System Software

## SureServo Pro configuration software

SureServo Pro is an optional free downloadable configuration software package for the SureServo drives. With SureServo Pro installed, the personal computer may be directly connected to the servo drive's serial port via the PC's RS-232 serial port*. A sixfoot configuration cable (SVC-PCCFG-CBL, \$18.00) is available to make the connection between the drive serial port and PC DB-9 serial port simple.
*Note: Use our USB-RS232 converter cable in conjunction with the SVC-PCCFGCBL cable on PCs having only USB ports.

## Features

- Quick Start - The basic setup when you have limited time and just want to gुet up and running ASAP.
- Maintenance keypad allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.
- Detailed - The complete setup for all the drive parameters
- Tune and check the servo response live using the scope feature.
- Upload and download the drive setup. Save the drive setup as a file for future use.
- Edit the drive setup
- View all drive faults
- Trend drive variables in real time


## System Requirements

- Windows 7, Windows 2000, XP Pro
- 24 MB of RAM
- 16 MB hard disk
- RS232 serial port or USB port
- Internet Explorer 4.0 or higher (for HTML help support)



## Parameter views

The SureServo Pro configuration tool logically organizes over 165 servo drive parameters into five tabbed groups. Each parameter has a factory default that usually allows the servo to run "out-of-the-box".
The parameters can be easily changed with available options or setting ranges displayed. Tuning modes and parameters can also be changed using SureServo Pro. After the parameters have been defined, the complete setup can be stored and archived. Drive configurations can be uploaded, edited, saved, and downloaded as often as necessary.

Parameter View Example Screen - Basic Parameters


## SureServo Software and Configuration Cables

| Product | Price | Description |
| :---: | :---: | :---: |
| SV-PRO | Free | SureServo Pro configuration sottware for use with all SureServo servo systems. FREE download from www.sureservo.com or www.automationdirect.com websites. |
| SV-PRO | \$9.00 | CD with SureServo Pro contiguration software |
| SVC-PCCFG-CBL | \$18.00 | Six-foot RS-232 communications cable; connects servo drive serial port to PC DB-9 serial port. <br> For PCS having only USB ports, use our USB-RS232 converter cable in conjunction with the SVC-PCCFG-CBL cable. |
| SVC-485CFG-CBL-2 * | \$10.00 | ZIPLink SureServo amplifier configuration cable, 6 -pin IEEE 1394 connector to RJ45 connector, shielded, twisted pair, 2.0 meter ( 6.6 ft .) length. Use this cable in conjunction with our USB-485M serial adapter to connect any SureServo amplifier to a PC. Eliminates the need to reprogram networked servo drives from RS485 to RS232 when connecting to a PC. |
| * Refer to the ZIPLinks Wiring Solutions section for complete information regarding ZIPLink cable SUC-485CFG-CBL-2. |  |  |

## Suren servo AC Servo System Software

## SureServo Pro configuration software Parameter views (continued)

## Parameter View Example Screen - Monitor Parameters

| Detated Comlipuration |  |
| :---: | :---: |
|  |  |
| MONITOR PARAMETERS |  |
| P0.00-P 0.16 |  |
| P000-Sothware Version | Eain |
| P0.01- Dive Foult Code | De Mofail Meser |
| P0.02- Dive Status (Front panel display) | Dmanitetespentmmentaval - - - - |
| P0.03-Analog Monitor Outputs |  |
| P0.04-Status Monitor 1 | 00 Mator Feesback Puste Number - |
| P005-Status Monitor 2 | 00 Motar Feestosck Puthe Number |
| P0 06 - Status Monitor 3 | 00 Matar Feestack Pulte Number |
| P007-Status Monitor 4 | 00. Malar Feedback Pulue Number |
| P0.08-Stetus Monitor 5 | 00. Mota Feedbeck Pulte Number * |
|  antered hae manudy siter an upioad operation P0.09 through POO 16 are and coriguathe fion the SureSevo Kespad |  |

Parameter View Example Screen - Extended Parameters


## Parameter View Example Screen - Communication Parameters

| Detatescomiguraion |  |
| :---: | :---: |
|  |  |
| COMMUNICATION PARAMETERS |  |
| P3.00-P3.07 |  |
| P3.00-Communication Address | I |
| P301-Transmission Speed | Eiswome |
| P302-Communication Protocol | Pmadouriumociail |
| P303-Communication Fault Action |  |
| P3.04-Communication Watchdog Time Out | 10 |
| P3.05-Communication Selection | 00. RS.232 $\quad$ - |
| P3.06-Resemed |  |
| P307-Communication Response Delay Time | $\sqrt{0}$ |

## Maintenance screen

A maintenance keypad allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.


## Scope

SureServo Pro includes a powerful scope function that allows the user to have as many as three channels of data displayed simultaneously. Each channel has a drop-down table to select the data to be displayed. The scope also has a trigger mode and timebase selection. This function is a valuable tool for tuning SureServo drives.


## Sure $\underset{\text { servo }}{\text { AC Servo Drive Specifications }}$

Servo drive overview
Keypad
Five Function keys:
MODE: Press to select or change mode
LED Display
The LED display has 5 full digits and is used to indicate servo status and alarms

NEXT: Press to shift left
UP: Press to increase values
DOWN: Press to decrease values
ENTER: Press to enter value


## I/O Interface

50-pin connector for interfacing the host controller (such as DirectLOGIC PLC) and other types of I/O signals.

Use our ZIPLink kit which provides DINrail mounted screw terminals for easy connection.

- Command inputs:
- Pulse and Direction
- Encoder Follower
- Analog Velocity/Torque
- (8) Digital Inputs
- (5) Digital Outputs
- (2) Analog Monitors
- Encoder Output (scalable)

$$
A+, A-, B+, B-, Z+, Z-
$$

Motor Output Terminal The servo motor power cable is connected to $\mathrm{U}, \mathrm{V}$ and W. Use our factory made and tested cables available in $10,20,30$ or 60 foot lengths for easy connection.

## Regenerative

Resistor Terminal

1. When the internal regenerative resistor is used, the $P$ and $D$ terminal are connected together while the $P$ and $C$ connection is left open.
2. When an external regenerative resistor is used, it is connected across the P and C terminals while the $P$ and $D$ connection is left open. Use our factory approved resistors for "sure" results.

## SureServo systems run "out-of-the-box"... but may be reconfigured for many applications!

The SureServo drives are fully digital and include over 165 programmable parameters. For convenience, the parameters are grouped into five categories:

1) Monitor parameters
2) Basic parameters
3) Extended parameters
4) Communication parameters
5) Diagnostic parameters.

All parameters have commonly used default values which allow you to operate the SureServo system "out-of-the-box". However, the programmability and large variety of parameters make the SureServo systems suitable for a very broad range of applications, including almost all types of general purpose industrial machinery such as assembly, test, packaging, machine tool, and robotics.

## Sure servo AC Servo Drive Specifications

Servo drive specifications

| Gencral Drive Specifioations |  |
| :---: | :---: |
| Permissible Frequency | $50 / 60 \mathrm{~Hz} \pm 5 \%$ |
| Encoder Resolution / Feedback Resolution | 2500 lines / 10000 ppr |
| Control of Main Circuit | SVPWM (Space Vector Pulse Width Modulation) Control |
| Tuning Modes | Easy / Auto / Manual |
| Dynamic Brake | Built-in control |
| Analog Monitor Outputs (2) | Monitor signal can be set by parameters (Output voltage range: $\pm 8 \mathrm{~V}$; Resolution: $12.8 \mathrm{mV} / \mathrm{count}$ ) |
| 8 Programmable Digital Inputs (45 selectable functions) | Servo enable, Alarm reset, Gain switching, Pulse counter clear, Fault stop, CW/CCW over-travel |
|  | Internal parameter selection, Torque limit activation, Velocity limit activation, Control mode selection |
| Scalable Encoder Output | Encoder signal output A, /A, B, /B, Z /Z, Line Driver |
| 5 Programmable Outputs (9 selectable indicators) | Servo ready, Servo On, Low velocity, Velocity reached, In Position, Torque limiting, Servo fault, Electromagnetic brake control, Home search completed |
| Communication Interface | RS-232 / RS-485 / RS-422 / Modbus ASCII \& RTU up to 115k Baud |
| Protective Functions | Overcurrent, Overvoltage, Undervoltage, Overload, Excessive velocity/position error, Encoder error, Regeneration error, Communication error |
| Installation Site | Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust) |
| Altitude | 1000 m [ 3281 tt above sea level - maximum |
| Operating Temperature | 0 to $55^{\circ} \mathrm{C}$ [32 to $131^{\circ} \mathrm{F}$ ] (If operating temperature is above $55^{\circ} \mathrm{C}$, forced cooling is required). For long-term reliability, the ambient temperature of SureServo systems should be under $45^{\circ} \mathrm{C}\left(113^{\circ} \mathrm{F}\right)$. |
| Storage Temperature | $-20^{\circ}$ to $65^{\circ} \mathrm{C}\left(-4^{\circ}\right.$ to $\left.149^{\circ} \mathrm{F}\right)$ |
| Humidity | 0 to 90\% (non-condensing) |
| Vibration | $9.81 \mathrm{~m} / \mathrm{s}^{2}(1 \mathrm{G})$ less than $20 \mathrm{~Hz}, 5.88 \mathrm{~m} / \mathrm{s}^{2}(0.6 \mathrm{G}) 20$ to 50 Hz |
| Protection | IP 20 |
| Agency Approvals | CE; UL listed (U.S. and Canada) |


and Lights

Stacklights

## Sure servo AC Servo Drive Specifications

## Servo drive specifications (continued)

| Model and Mode Specific Drive Specifications |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | AC Servo Model |  | SVA-2040 |  |  | SVA-2100 |  |  | SVA-2300 |  |
|  | Price |  | \$488.00 |  |  | \$632.00 |  |  | \$1,054.00 |  |
|  | Voltage Phase |  | Single-phase or Three-phase |  |  |  |  |  | Three-phase |  |
|  | Voltage and Frequency Range |  | 3-phase: 170~255 VAC @ $50 / 60 \mathrm{~Hz} \pm 5 \%$; 1-phase: 200-255 VAC @ $50 / 60 \mathrm{~Hz} \pm 5 \%$ |  |  |  |  |  | 170~255 VAC @ 50/60 Hz $\pm 5 \%$ |  |
|  | Main Circuit Input Current | Single Phase | 3.4A @ 400W |  |  | 8.0A @ 1kW |  |  | - |  |
|  |  | Three Phase | 2.6A @ 400W |  |  | 6.2A@1kW |  |  | 13.6 A @ 3kW |  |
|  | Main Circuit Inrush Current |  | 44A |  |  | 77A |  |  | 87A |  |
|  | Main Circuit Power Cycling |  | Maximum 1 power cycle per minute |  |  |  |  |  |  |  |
|  | Control Circuit Current and Voltage |  | 43 mA @ 200~255 VAC, 1 phase |  |  |  |  |  |  |  |
|  | Control Circuit Inrush Current |  | 32A maximum |  |  |  |  |  |  |  |
|  | Cooling System |  | Natural Air Circulation |  |  | Internal Cooling Fan |  |  |  |  |
|  | Drive Heat Loss * | Motor driven * | SVL-201(B) | SVL-202(B) | SVL-204(B) | SVL-207(B) | SVL-210(B) | SVM-210(B) | SVM-220(B) | SVM-230(B) |
|  |  | Heat Loss | 12W | 15W | 20W | 35W | 45W | 50W | 75 W | 80W |
|  | Weight |  | $1.5 \mathrm{~kg}[3.3 \mathrm{lb}]$ |  |  | 2kg [41b] |  |  | 3kg [71b] |  |
|  | Max. Input Pulse Frequency |  | Max. 500 kpps (Line driver); Max. 200 kpps (Open collector) |  |  |  |  |  |  |  |
|  | Pulse Type |  | Pulse + Direction, A phase + B phase Quadrature, CCW pulse + CW pulse |  |  |  |  |  |  |  |
|  | Command Source |  | External pulse train / Onboard indexer |  |  |  |  |  |  |  |
|  | Smoothing Strategy |  | Low-pass and P-curve filter |  |  |  |  |  |  |  |
|  | Electronic Gear |  | Electronic gear N/M multiple; N: 1~32767, M: 1~32767(1/50<N/M<200) |  |  |  |  |  |  |  |
|  | Torque Limit Operation |  | Set by parameters or by analog input |  |  |  |  |  |  |  |
|  | Feed Forward Compensation |  | Set by parameters |  |  |  |  |  |  |  |
| Velocity Control Mode | Analog Input Command | Voltage Range | Bipolar $\pm 10 \mathrm{VDC}$ |  |  |  |  |  |  |  |
|  |  | Input Resistance | $10 \mathrm{k} \Omega$ |  |  |  |  |  |  |  |
|  |  | Time Constant | 2.2 ¢ |  |  |  |  |  |  |  |
|  |  | Resolution | (Varies with input voltage) 13 bits @ 0V $\sim 1 V ; 13 \sim 10$ bits @ 1V 2V; 10 bits @ 2V 10 V |  |  |  |  |  |  |  |
|  | Speed Control Range |  | $1: 5000$ |  |  |  |  |  |  |  |
|  | Command Source |  | External analog signal / Onboard indexer |  |  |  |  |  |  |  |
|  | Smoothing Strategy |  | Low-pass and S-curve filter |  |  |  |  |  |  |  |
|  | Torque Limit Operation |  | Set by parameters or via analog input |  |  |  |  |  |  |  |
|  | Frequency Response Characteristic |  | Maximum 450 Hz |  |  |  |  |  |  |  |
|  | Speed Accuracy (at rated rotation speed) |  | 0.01\% or less at 0 to $100 \%$ load fluctuation |  |  |  |  |  |  |  |
|  |  |  | $0.01 \%$ or less at $\pm 10 \%$ power fluctuation |  |  |  |  |  |  |  |
|  |  |  | $0.01 \%$ or less at 0 to $50^{\circ} \mathrm{C}$ ambient temperature fluctuation |  |  |  |  |  |  |  |
| Torque Control Mode | Analog Input Command | Voltage Range | Bipolar $\pm 10$ VDC |  |  |  |  |  |  |  |
|  |  | Input Resistance | $10 \mathrm{k} \Omega$ |  |  |  |  |  |  |  |
|  |  | Time Constant | 2.2 Hs |  |  |  |  |  |  |  |
|  |  | Resolution | 10 bits |  |  |  |  |  |  |  |
|  | Permissible Time for Overload |  | 8 sec. under 200\% rated output |  |  |  |  |  |  |  |
|  | Command Source |  | External analog signal / Onboard indexer |  |  |  |  |  |  |  |
|  | Smoothing Strategy |  | Low-pass filter |  |  |  |  |  |  |  |
|  | Speed Limit Operation |  | Set by parameters or via analog input |  |  |  |  |  |  |  |
| * Drive heat loss varies depending upon which motor is connected to the drive. |  |  |  |  |  |  |  |  |  |  |

## Sure $\underset{\text { servo }}{ }$ AC Servo Motor Specifications

Servo motor overview


## Suresving AC Servo Motor Specifications



## Sure servo AC Servo System Wiring

## Standard wiring examples

This wiring diagram shows basic wiring only, and additional wiring configurations are possible for some I/O.
Refer to the "Installation and Wiring" chapter of the User Manual for more detalled wiring information.
Position (Pr \& Pt) Control Modes
$\dagger$ Remove Jumper at D if using External Resistor


Modbus communication to PC, PLC, etc

* Use connection kit part \#s ZL-RTB50 \& ZL-SVC-CBL-50(-x) for CN1 terminal connections.
** Use cable part \# SVC-Exx-OxO for CN2 terminal connections.
*** Use cable part \# SVC-MDCOM-CBL for CN3 terminal Modbus network connections.


## Sure servo AC Servo System Wiring

## Standard wiring examples (continued)

This wiring diagram shows baSic wiring only, and additional wiring configurations are possible for some I/O.
Refer to the "Installation and Wiring" chapter of the User Manual for more detailed wiring information.

## Velocity and Torque Control Modes



* Use connection kit part \#s ZL-RTB50 \& ZL-SVC-CBL-50(-x) for CN1 terminal connections.
** Use cable part \# SVC-Exx-0x0 for CN2 terminal connections.
*** Use cable part \# SVC-MDCOM-CBL for CN3 terminal Modbus network connections.


## Sure $\underset{\text { servo }}{\text { AC Servo System Dimensions }}$

Servo drive dimensions
SVA-2040


RECOMMENDED USER SUPPLIED MOUNTING SCREW IS M6.
Tighten to 14 KGF.CM (1.37 N•M).
UNITS: mm (in)


SVA-2100


## Sure servo AC Servo System Dimensions

Servo drive dimensions (continued)
SVA-2300


Note: Recommended user supplied mounting screw is M6. Tighten to 14 KGF.CM (1.37 N•M).

(Inch values are for reference only.)


## Servo motor dimensions




| SureServo ${ }^{\oplus}$ Motor Dimensions -100W-750W Low Inertia |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Dimension | SVL-201(B) | SVL-202(B) | SVL-204(B) | SVL-207(B) |
| A | 40 [1.575] | 60 [2.362] |  | 80 [3.15] |
| B | 4.5 [0.1772] | 5.5 [0.2165] |  | 6.6 [0.2598] |
| C | 46 [1.811] | 70 [2.756] |  | 90 [3.543] |
| D | $8+0.0 /-0.009$ (8h6) | $14+0.0 /-0.011$ (14h6) |  | $19+0.0-0.013$ (19h6) |
| E | $30+0.0 /-0.021$ (30h7) | $50+0.0 /-0.025$ (50h7) |  | $70+0.0 /-0.030$ (70h7) |
| $\begin{gathered} \text { F } \\ \text { (w/o brake) } \end{gathered}$ | 100.1 [3.941] | 102.4 [4.032] | 124.4 [4.898] | 135 [5.315] |
| F (with brake) | 135.7 [5.343] | 137 [5.394] | 159 [6.26] | 171.6 [6.756] |
| G | 25 [0.98] | 30 [1.18] |  | 35 [1.38] |
| H | 5 [0.197] | 6 [0.236] |  | 8 [0.315] |
| I | 2.5 [0.098] | 3 [0.118] |  |  |
| Cable length | 300 mm (12 inches) |  |  |  |
| UNITS: mm [in]. (Inches are for reference only; not included on diameter dimensions for accuracy.) |  |  |  |  |

## Suren: AC Servo System Dimensions <br> servo

Drives
Soft Starters

Motors

Power Transmission

| SureServo Motor Dimensions -1000W Low Inertia |  |
| :---: | :---: |
| Dimension | SVL-210(B) |
| A | $100[3.937]$ |
| B | $9[0.3543]$ |
| C | $115+0.0 /-0.2[4.528]$ |
| D | $22+0.0 /-0.013(2226)$ |
| E | $95+0.0 /-0.035(95 h 7)$ |
| F $\mathbf{~ w} / \mathbf{~ b r a k e ) ~}$ | $158[6.22]$ |
| F |  |
| with brake) | $190[7.48]$ |
| G | $45[1.77]$ |
| H | $17[0.669]$ |
| I | $7[0.28]$ |

UNITS: mm [in] (Inches are for reference only; not included on diameter dimensions for accuracy.)

Medium inertia models SVM-210(B), $\underline{\text { SVM-220(B), SVM-230(B) }}$


| Dimension | SVM-210(B) | SVM-220(B) | SVM-230(B) |
| :---: | :---: | :---: | :---: |
| A | 130 [5.118] |  |  |
| B | 9 [0.3543] |  |  |
| C | $145+0.2 /-0.2$ [5.709] |  | [774] |
| D | $22+0.0 /-0.013$ (22h6) |  | 5h6) |
| E | $110+0.0 /-0.035$ (110h7) | 114.3 | 4.3h7) |
| $\begin{gathered} \text { F } \\ \text { (w/o brake) } \end{gathered}$ | 143 [5.63] | 164 [6.457] | 212 [8.35] |
| $\begin{gathered} \text { F } \\ \text { (with brake) } \end{gathered}$ | 181 [7.126] | 213 [8.386] | 258 [10.16] |
| G | 55 [2.17] | 75 [2.95] |  |
| H | 15 [0.591] | 20 [0.787] |  |
| I | 4 [0.157] |  |  |
| UNITS: mm [in] (Inches are for reference only; not included on diameter dimensions for accuracy.) |  |  |  |

## Sure $\underset{\text { servo }}{\sim A C}$ Servo System Accessories

Accessories

## External Regeneration Resistors

Use external resistors to provide additional regenerative capacity and to dissipate heat away from the servo drive.

| Part Number | Resistance | Sureservo Drives | Price |
| :--- | :---: | :---: | :---: |
| GS-25PO-BR | $40 \Omega$ | $\underline{\text { SVA-2040 }}$ | $\$ 75.00$ |
| GS-2010-BR-ENC | $20 \Omega$ | $\underline{\text { SVA-2100, }} \underline{\text { SVA-2300 }}$ | $\$ 223.00$ |

## AC Line Filters

Input EMI filters reduce electromagnetic interference or noise on the input side of the servo drive. They are required for CE compliance and recommended for installations prone to or sensitive to electromagnetic interference.

| Surceservo Drives | AC Input Power | EMI Filter Rating | EMI Filter Part Number | Priog |
| :---: | :---: | :---: | :---: | :---: |
| SVA-2040 | Single-Phase | $250 \mathrm{~V}, 1$-phase, 20A | 20DRT1W3S | \$76.00 |
|  | Three-Phase | 250V, 3-phase, 10A | 10TDT1W4C | \$81.00 |
| SVA-2100 | Single-Phase | $250 \mathrm{~V}, 1$-phase, 20A | 20DRT1W3S | \$76.00 |
|  | Three-Phase | 250V, 3-phase, 10A | 10TDT1W4C | \$81.00 |
| SVA-2300 | Three-Phase | 250V, 3-phase, 26A | 26TDT1W4C | \$113.00 |
|  | Note: These EMI Filters are electrically Compatible with the SURESERVO DRIVES. HOWEVER, THEY ARE INTENDED TO BE MOUNTED next to the servo drive. Do not mount the filter under the drive. The drive mounting holes on these units are intended to be USED only with AutomationDirect's line of VFDs. |  |  |  |

## Edison Fuses \& Fuji Contactors

| Sureservoe Drives | Input Typs | Input Voltage | Edison Fuse <br> - Class GC | Price* | Contactor** | Price |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SVA-2040 | Main Input Power | 230V 3-Phase | HCTR4 | \$86.00 | SC-E02-XXX | varies |
| SVA-2100 |  |  | HCTR7-5 | \$98.00 | SC-E03-XXX | varies |
| SVA-2300 |  |  | HCTR15 | \$80.00 | SC-E04-XXX | varies |
| SVA-2040 |  | 230V 1-phase | HCTR4 | \$86.00 | SC-E02-XXX | varies |
| SVA-2100 |  |  | HCTR10 | \$87.00 | SC-E03-XXX | varies |
| $\begin{aligned} & \frac{S V A-2040}{S V A-2100} \\ & \hline S V A-2300 \\ & \hline \end{aligned}$ | Control Input Power | 230V 1-phase | HCTR2-5 | \$89.00 |  |  |
| * Fuses are sold in packages of 10. <br> ** Note: For contactors, $x x x=$ coil voltage (for example, $\underline{S C-E 02-220 V A C) . ~}$ |  |  |  |  |  |  |



Resistor GS-25PO-BR


AC Line Filter 10TD1W4C


The SureGear PGA and PGB series easily mates to SureServo motors.
Everything you need to mount your SureServo motor is included!
It is the perfect solution for applications such as gantries, injection-molding machines, pick-and-place automation, and linear slides.

Quickly and easily configure a system online:
http://www.sureservo.com/gearbox/selector

SureGear Precision Gearboxes for Servo motors Sure *gear

IN-LINE

## Pushbuttons

Tough on the outside, precision quality on the inside

57 models, four gear ratios available


## SureGear ${ }^{\circledR}$ Servo Gearbox Overview

## PGA In-line Series

The SureGear PGA series of high-precision servo gear reducers is an excellent choice for applications that require good accuracy and reliability at an exceptional value. This in-line planetary gear reducer has a thread-in mounting style, along with a level of precision and torque capacity that is best in its class. Offered in a concentric shaft design with a maximum seven arc-min backlash rating, the SureGear PGA series is an accurate, high-performance, and cost effective solution for any OEM.
The machining quality of the SureGear PGA helical planetary gears provides a very quiet and more efficient reducer than other competitive products that are similarly priced. The SureGear PGA series easily mates to SureServo motors, and is the perfect solution for applications such as gantries, injection-molding machines, pick-and-place automation, and linear slides.

## PGB Right-angle Series

The SureGear PGB series of high-precision right-angle servo gear reducers is an excellent choice for applications that require a more compact footprint.
The PGB right-angle planetary gear reducers offer similar technical specifications to the PGA series in-line gear reducers, and provides the customer with an excellent solution when space and clearance requirentents are limited.
Offered with a six arc-minhacklash rating for 2-stage and nine arcmin backlash for 3-stage, the SureGear PGB series performs to OEMs' demanding expectations.

## Features

- Industry-standard mounting dimensions
- Thread-in mounting style
- Bestin-class backlash
- Four gुear ratios available (5:1, 10:1, 15:1, 25:1)
- Mounting hardware included for attaching to SureServo motors
- Helical-cut planetary gुears for quiet operation and reduced vibration
- Right-angle reducer utilizes a spiral bevel gुear; motor can be located at a $90^{\circ}$ position from the rectucer, providing a more compact footprint
- Uncaged needle roller forkigh rigidity and torque
- Adapter bushing consimple and effective attachment to most servo motors $\qquad$
- Highin-viscosity, anti-separation grease does not migrate away from the gुears; no leakaģe through the seal
- Maintenance free: No need to replace the grease for the life of the unit
- At nominal speed, service life is 20,000 hours
- Can be positioned in any orientation
- IP55 environmental ratino
- 5-year warranty

Applications

- Gantries
- Injection-molding machines
- Pick-and-place automation
$\qquad$
- $\quad \begin{aligned} & \square \\ & \square\end{aligned}$
- Linear slides
- Packaging machines
- Conveyors


## SureGear ${ }^{\circledR}$ Servo Gearbox Selection

| Surehear ${ }^{\circledR}$ Servo Cearbox Sclection |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Gear Ratio | SureGear Gearbox | Frame Size (mm) | Motor Nominal Output Torque ( $\mathrm{N} \cdot \mathrm{m}$ [lb•in] ) | Combination Nominal Output Torque ( $\mathrm{N} \cdot \mathrm{m}[\mathrm{lb} \cdot \mathrm{in}]$ ) | Combination Nominal Output Speed ( rpm ) | Combination Max Output Speed ( rpm ) | Available Load Inertia <br> @ 5:1 Mismatch * <br> ( $\mathrm{kg} \cdot \mathrm{cm}^{2}$ [lb $\left.\cdot \mathrm{in} \cdot \mathrm{s}^{2}\right]$ ) |  |
|  |  | (PGx $=$ PGA or PGB) |  |  |  |  |  | PGAxxx-xxxx | PGBxxx-xxxx |
| $\begin{aligned} & \text { SVL- } \\ & \text { 201(B) } \end{aligned}$ | 5:1 | PGA050-05A1 | 50 | 0.32 [2.8] | 1.59 [14.1] | 600 | 1,000 | 2.85 [0.003] | - |
|  | 10:1 | PGA050-10A1 |  |  | 3.18 [28.1] | 300 | 500 | 12.00 [0.011] |  |
|  | 15:1 | PGA050-15A1 |  |  | 4.77 [42.2] | 200 | 333 | 25.88 [0.023] |  |
|  | 25:1 | PGA050-25A1 |  |  | 7.95 [70.4] | 120 | 200 | 72.50 [0.064] |  |
|  | 5:1 | PGx070-05A1 | 70 |  | 1.59 [14.1] | 600 | 1,000 | 1.83 [0.002] | -2.50 [-0.002] ** |
|  | 10:1 | PGx070-10A1 |  |  | 3.18 [28.1] | 300 | 500 | 9.40 [0.008] | -8.00 [-0.007] ** |
|  | 15:1 | PGx070-15A1 |  |  | 4.77 [42.2] | 200 | 333 | 21.38 [0.019] | 17.33 [0.015] |
|  | 25:1 | PGx070-25A1 |  |  | 7.95 [70.4] | 120 | 200 | 60.63 [0.054] | 49.38 [0.044] |
|  | 5:1 | PGx070-05A2 |  | 0.64 [5.7] | 3.20 [28.3] | 600 | 1,000 | 18.50 [0.016] | 34.50 [0.031] |
|  | $10 \cdot 1$ | PGx070-10A2 |  |  | 6.40 [56.6] | 300 | 500 | 76.00 [0.067] | 140.00 [0.124] |
| SVL- | 15:1 | PGx070-15A2 |  |  | 9.60 [85.0] | 200 | 333 | 171.00 [0.151] | $355.95[0.375]$ |
| $202(\mathrm{~B})$ | 25:1 | PGx070-25A2 |  |  | 16.00 [141.6] | 120 | 200 | 481.25 [0.426] | 990.63 [0.876] |
|  | 15:1 | PGB090-15A2 | 90 |  | 9.60 [85.0] | 200 | 333 |  | 1122.75 [0.993] |
|  | 25:1 | PGB090-25A2 |  |  | 16.00 [141.6] | 120 | 200 |  | 3125.00 [2.764] |
| $\begin{aligned} & \text { SVL- } \\ & 204(\mathrm{~B}) \end{aligned}$ | $5: 1$ | PGx070-05A2 | 70 | 1.27 [11.2] | 6.35 [56.2] | 600 | 1,000 | 38.50 [0.034] | 34.50 [0.031] |
|  | 10:1 | PGx070-10A2 |  |  | 12.70 [112.4] | 300 | 500 | 156.00 [0.138] | 140.00 [0.124] |
|  | 15:1 | PGB090-15A2 | 90 |  | 19.05 [168.6] | 200 | 333 |  | $290.25[0.257]$ |
|  | $25: 1$ | PGB090-25A2 |  |  | 31.75 [281.0] | 120 | 200 |  | 872.50[0.179] |
|  | $5: 1$ | PGA070-05A3 | 70 | 2.39 [21.2] | 11.95 [105.8] | 600 | 900 | 126.00 [0.111] | - |
|  | 5.1 | PGB090-05A3 | 90 |  | 11.95 [105.8] | 600 | 900 | - | 81.75 [0.072] |
| $\begin{gathered} \text { SVL- } \\ 207(B) \end{gathered}$ | 10:1 | PGx090-10A3 |  |  | 23.90 [211.5] | 300 | 450 | 465.00 [0.411] | 338.00 [0.299] |
|  | 15:1 | PGx090-15A3 |  |  | 35.85 [317.3] | 200 | 300 | 1053.00 [0.931] | 1080.00 [0.955] |
|  | $25 \cdot 1$ | PGx090-25A3 |  |  | 59.75 [528.8] | 120 | 180 | 2931.25 [2.593] | 3006.25 [2.659] |
|  | 5:1 | PGx090-05A4 |  | 3.30 [29.2] | 16.50 [146.0] | 600 | 900 | 252.50 [0.223] | 218.50[0.193] |
| SVL- | 10:1 | PGx090-10A4 |  |  | 33.00 [292.1] | 300 | 450 | 1020.00 [0.902] | 885.00 [0.783] |
| 210(B) | 15:1 | PGx120-15A4 | 120 |  | 49.50 [438.1] | 200 | 300 | 2295.00 [2.030] | 1867.50 [1.652] |
|  | 25:1 | PGx120-25A4 |  |  | 82.50 [730.2] | 120 | 180 | 6375.00 [5.639] | 5225.00 [4.622] |
|  | $5: 1$ | -PGA090-05A5 | 90 | 4.80 [42.5] | 24.00 [212.4] | 400 | 600 | 675.00 [0.597] |  |
|  | 10:1 | PGA090-10A5 |  |  | 48.00 [424.8] | 200 | 300 | 2710.00 [2.397] |  |
| SVM- | 5:1 | PGB120-05A5 | 120 |  | 24.00 [212.4] | 400 | 600 | - | 582.25 [0.515] |
| 210(B) | 10:1 | PGB120-10A5 |  |  | 48.00 [424.8] | 200 | 300 | - | 2385.00 [2.110] |
|  | 15:1 | PGx120-15A5 |  |  | 72.00 [637.3] | 133 | 200 | 6097.50 [5.393] | $5670.00[5.045]$ |
|  | 25.1 | PGx120-25A5 |  |  | 120.00 [1062.1] | 80 | 120 | 16937.50 [14.981] | 15787.50 [13.964] |
| $\begin{aligned} & \text { SUAA } \\ & 220(\mathrm{~B}) \end{aligned}$ | $5: 1$ | PGx120-05A6 |  | 9.40 [83.2] | 47.00 [416.0] | 400 | 600 | 1700.00 [1.504] | 1632.75 [1.444] |
|  | 10:1 | PGx120-10A6 |  |  | 94.00 [832.0] | 200 | 300 | 6800.00 [6.015] | 6588.00 [5.827] |
|  | $15 \cdot 1$ | PGx155-15A6 | 155 |  | 141.00 [1239.1] | 133 | 200 | 15300.00 [13.533] | 14384.25 [12.723] |
|  | 25:1 | PGx155-25A6 |  |  | 235.00 [2079.9] | 80 | 120 | 42500.00 [37.591] | 40112.50 [35.480] |
|  | 5:1 | PGB155-05A6 |  |  | 47.00 [416.0] | 400 | 600 | - | 1443.00 [1.276] |
|  | 10:1 | PGx-155-10A6 |  |  | 94.00 [832.0] | 200 | 300 | 6800.00 [6.015] | 5997.00 [5.304] |
| $\begin{aligned} & \text { SUtI- } \\ & 230(\mathrm{~B}) \end{aligned}$ | 5:1 | PGx120-05A6 | 120 | 14.30 [126.6] | 71.50 [632.8] | 400 | 600 | 5137.50 [4.544] | 5070.25 [4.485] |
|  | 10:1 | -PGx120-10A6 |  |  | 143.00 [1265.7] | 200 | 300 | 20550.00 [18.176] | 20338.00 [17.989] |
|  | 5:1 | PGB155-05A6 | 155 |  | 71.50 [632.8] | 400 | 600 | - | 4880.50 [4.317] |
|  | 10:1 | PGx155-10A6 |  |  | 143.00 [1265.7] | 200 | 300 | 20550.00 [18.176] | 19747.00 [17.466] |


A 5:1 inertia mismatch is a good target for design purposes. Systems with lower or higher mismatch may be possible, depending on operating conditions.
** This qearbox is NOT a suitable choice at a $5: 1$ mismatch. If inertia balancing is a selection criteria for your end use, please use a mismatch of 8:1 to 10:1.

## Pricing \& Specifications - In-Line Shaft PGA Series



## Sure節ear Precision Servo Gearboxes

Dimensions - In-Line Shaft PGA Series


SureGear PGA Series In-Line Shaft Gearboxes Dimension Drawing

Suretear ${ }^{\circledR}$ Precision Servo Gearhox Dimensions - In-Line Shaft PGA Series (dimensions = mm [in])

| Part Number | A | $B$ | C | $E$ | G | H | $J$ | $K$ | $L$ | M | $N$ | $P$ | Q | $\boldsymbol{R}$ | $S$ | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { PGA050-05A1 } \\ & \text { PGA050-10A1 } \end{aligned}$ | $\begin{gathered} 88.5 \\ {[3.48]} \end{gathered}$ | $\begin{gathered} 42.0 \\ {[1.65]} \end{gathered}$ | $\begin{gathered} 24.5 \\ {[0.96]} \end{gathered}$ | $\begin{gathered} 4.0 \\ {[0.16]} \end{gathered}$ | $\begin{gathered} \varnothing 50.0 \\ {[\varnothing 1.97]} \end{gathered}$ | $\begin{gathered} \varnothing 35.0 \\ {[\varnothing 1.38]} \end{gathered}$ | $\begin{gathered} \varnothing 12.0 \\ {[\emptyset 0.47]} \end{gathered}$ | $\begin{gathered} \varnothing 46.0 \\ {[\varnothing 1.81]} \end{gathered}$ | $\begin{gathered} \emptyset 30.0 \\ {[\emptyset 1.18]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 08.0 \\ {[\varnothing 0.31]} \end{gathered}$ | $\begin{aligned} & \text { M4- } \\ & 0.7 \times 9 \end{aligned}$ | $\begin{gathered} 044.0 \\ \text { [Ø0.731] } \end{gathered}$ | $\begin{aligned} & \text { M4- } \\ & 0.7 \times 8 \end{aligned}$ | $\begin{gathered} 4.0 \\ {[0.16]} \end{gathered}$ | $\begin{gathered} 4.0 \\ {[0.16]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA050-15A1 } \\ & \text { PGA050-25A1 } \end{aligned}$ | $\begin{gathered} 105.0 \\ {[4.13]} \end{gathered}$ | $\begin{gathered} 42.0 \\ {[1.65]} \end{gathered}$ | $\begin{gathered} 24.5 \\ {[0.96]} \end{gathered}$ | $\begin{gathered} 4.0 \\ {[0.16]} \end{gathered}$ | $\begin{gathered} \varnothing 50.0 \\ {[\varnothing 1.97]} \end{gathered}$ | $\begin{gathered} \emptyset 35.0 \\ {[\varnothing 1.38]} \end{gathered}$ | $\begin{gathered} \varnothing 12.0 \\ {[\varnothing 0.47]} \end{gathered}$ | $\begin{gathered} \emptyset 46.0 \\ {[\varnothing 1.81]} \end{gathered}$ | $\begin{gathered} \text { Ø30.0 } \\ {[\varnothing 1.18]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \square 88.0 \\ {[\varnothing 0.31]} \end{gathered}$ | $\begin{aligned} & \text { M4- } \\ & 0.7 \times 9 \end{aligned}$ | $\begin{gathered} 044.0 \\ {[\emptyset 0.731]} \end{gathered}$ | $\begin{aligned} & \text { M4- } \\ & 0.7 \times 8 \end{aligned}$ | $\begin{gathered} 4.0 \\ {[0.16]} \end{gathered}$ | $\begin{gathered} 4.0 \\ {[0.16]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA070-05A1 } \\ & \text { PGA070-10A1 } \end{aligned}$ | $\begin{aligned} & 112.0 \\ & {[4.41]} \end{aligned}$ | $\begin{gathered} 52.0 \\ {[2.05]} \end{gathered}$ | $\begin{gathered} 36.0 \\ {[1.42]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \varnothing 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} \varnothing 52.0 \\ {[\emptyset 2.05]} \end{gathered}$ | $\begin{gathered} \varnothing 16.0 \\ {[\emptyset 0.63]} \end{gathered}$ | $\begin{gathered} 046.0 \\ {[\varnothing 1.81]} \end{gathered}$ | $\begin{gathered} \varnothing 30.0 \\ {[\varnothing 1.18]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \emptyset 8.0 \\ {[\varnothing 0.31]} \end{gathered}$ | $\begin{aligned} & \text { M4- } \\ & 0.7 \times 9 \end{aligned}$ | $\begin{gathered} \varnothing 62.0 \\ {[Ø 2.44]} \end{gathered}$ | $\begin{aligned} & \text { M5- } \\ & 0.8 \times 10 \end{aligned}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA070-05A2 } \\ & \text { PGAO70-10A2 } \end{aligned}$ | $\begin{aligned} & 115.0 \\ & {[4.53]} \end{aligned}$ | $\begin{gathered} 65.0 \\ {[2.56]} \end{gathered}$ | $\begin{gathered} 36.0 \\ {[1.42]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \varnothing 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} \varnothing 52.0 \\ {[Ø 2.05]} \end{gathered}$ | $\begin{gathered} \varnothing 16.0 \\ {[\varnothing 0.63]} \end{gathered}$ | $\begin{gathered} \varnothing 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} \varnothing 50.0 \\ {[\varnothing 1.97]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \varnothing 14.0 \\ {[\varnothing 0.55]} \end{gathered}$ | $\begin{aligned} & \text { M5- } \\ & 0.8 \times 11 \end{aligned}$ | $\begin{gathered} \text { Ø62.0 } \\ {[Ø 2.44]} \end{gathered}$ | $\begin{gathered} \text { M5- } \\ 0.8 \times 10 \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |
| PG | $\begin{aligned} & 130.0 \\ & {[5.12]} \end{aligned}$ | $\begin{gathered} 80.0 \\ {[3.15]} \end{gathered}$ | $\begin{gathered} 36.0 \\ {[1.42]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |  | $\begin{gathered} \varnothing 52.0 \\ {[\emptyset 2.05]} \end{gathered}$ | $\begin{gathered} \emptyset 16.0 \\ {[\emptyset 0.63]} \end{gathered}$ | $\begin{gathered} \text { Ø90.0 } \\ {[\emptyset 3.54]} \end{gathered}$ | $\begin{gathered} \emptyset 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} \varnothing 19.0 \\ {[\varnothing 0.75]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 13 \end{gathered}$ | $\begin{gathered} \varnothing 62.0 \\ {[\varnothing 2.44]} \end{gathered}$ | $\begin{gathered} \text { M5- } \\ 0.8 \times 10 \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA070-15A1 } \\ & \text { PGA070-25A1 } \end{aligned}$ |  | $\begin{gathered} 52.0 \\ {[2.05]} \end{gathered}$ | $\begin{gathered} 36.0 \\ {[1.42]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |  | $\begin{gathered} \varnothing 52.0 \\ {[Ø 2.05]} \end{gathered}$ | $\begin{gathered} \varnothing 16.0 \\ {[\emptyset 0.63]} \end{gathered}$ | $\begin{gathered} 046.0 \\ {[\varnothing 1.81]} \end{gathered}$ | $\begin{gathered} \emptyset 30.0 \\ {[\varnothing 1.18]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \boxed{08.0} \\ {[\varnothing 0.31]} \end{gathered}$ | $\begin{aligned} & \text { M4- } \\ & 0.7 \times 9 \end{aligned}$ | $\begin{gathered} \varnothing 62.0 \\ {[Ø 2.44]} \end{gathered}$ | $\begin{gathered} \text { M5- } \\ 0.8 \times 10 \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |
| $\begin{aligned} & \text { PGAO70-15A2 } \\ & \text { PGAO70-25A2 } \end{aligned}$ | $\begin{aligned} & 136.0 \\ & {[5.35]} \end{aligned}$ | $\begin{gathered} 65.0 \\ {[2.56]} \end{gathered}$ | $\begin{gathered} 36.0 \\ {[1.42]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \emptyset 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} \text { Ø52.0 } \\ {[Ø 2.05]} \end{gathered}$ | $\begin{gathered} \emptyset 16.0 \\ {[\emptyset 0.63]} \end{gathered}$ | $\begin{gathered} \emptyset 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} \varnothing 50.0 \\ {[\varnothing 1.97]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} \varnothing 14.0 \\ {[\varnothing 0.55]} \end{gathered}$ | $\begin{gathered} \text { M5- } \\ 0.8 \times 11 \end{gathered}$ | $\begin{gathered} \varnothing 62.0 \\ {[\emptyset 2.44]} \end{gathered}$ | $\begin{gathered} \text { M5- } \\ 0.8 \times 10 \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |
| PGA090-10A3 | $\begin{aligned} & 153.0 \\ & {[6.02]} \end{aligned}$ | $\begin{gathered} 80.0 \\ {[3.15]} \end{gathered}$ | $\begin{gathered} 46.0 \\ {[1.81]} \end{gathered}$ | $\begin{gathered} 7.0 \\ {[0.28]} \end{gathered}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \text { Ø68.0 } \\ {[\emptyset 2.68]} \end{gathered}$ | $\begin{gathered} \varnothing 22.0 \\ {[\varnothing 0.87]} \end{gathered}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \varnothing 70.0 \\ {[\varnothing 2.76]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} \varnothing 19.0 \\ {[\emptyset 0.75]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 13 \end{gathered}$ | $\begin{gathered} \emptyset 80.0 \\ {[Ø 3.15]} \end{gathered}$ | $\begin{aligned} & \text { M6- } \\ & 1.0 \times 12 \end{aligned}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA090-05A4 } \\ & \text { PGA090-10A4 } \end{aligned}$ | $\begin{aligned} & 170.0 \\ & {[6.69]} \end{aligned}$ | $\begin{aligned} & 100.0 \\ & {[3.94]} \end{aligned}$ | $\begin{gathered} 46.0 \\ {[1.81]} \end{gathered}$ | $\begin{gathered} 7.0 \\ {[0.28]} \end{gathered}$ | $\begin{gathered} \emptyset 90.0 \\ {[\emptyset 3.54]} \end{gathered}$ | $\begin{gathered} \text { Ø68.0 } \\ {[Ø 2.68]} \end{gathered}$ | Ø22.0 <br> [00.87] | $\begin{aligned} & \varnothing 115.0 \\ & {[Ø 4.53]} \end{aligned}$ | $\begin{gathered} \varnothing 95.0 \\ {[\varnothing 3.74]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ | $\begin{aligned} & \emptyset 22.0 \text { * } \\ & {[\varnothing 0.87]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 17 \end{gathered}$ | $\begin{gathered} \emptyset 80.0 \\ {[Ø 3.15]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 12 \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA090-05A5 } \\ & \text { PGA090-10A5 } \end{aligned}$ | $\begin{gathered} 165.0 \\ {[6.50]} \end{gathered}$ | $\begin{aligned} & 130.0 \\ & {[5.12]} \end{aligned}$ | $\begin{gathered} 46.0 \\ {[1.81]} \end{gathered}$ | $\begin{gathered} 7.0 \\ {[0.28]} \end{gathered}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \text { Ø68.0 } \\ {[\emptyset 2.68]} \end{gathered}$ | $\begin{gathered} \emptyset 22.0 \\ {[\emptyset 0.87]} \end{gathered}$ | $\begin{aligned} & \varnothing 145.0 \\ & {[\varnothing 5.71]} \end{aligned}$ | $\begin{aligned} & \varnothing 110.0 \\ & {[\varnothing 4.33]} \end{aligned}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ | $\begin{aligned} & \varnothing 22.0^{*} \\ & {[\emptyset 0.87]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 17 \end{gathered}$ | $\begin{gathered} \emptyset 80.0 \\ {[Ø 3.15]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 12 \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA090-15A3 } \\ & \text { PGA090-25A3 } \end{aligned}$ | $\begin{aligned} & 175.0 \\ & {[6.89]} \end{aligned}$ | $\begin{gathered} 80.0 \\ {[3.15]} \end{gathered}$ | $\begin{gathered} 46.0 \\ {[1.81]} \end{gathered}$ | $\begin{gathered} 7.0 \\ {[0.28]} \end{gathered}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \emptyset 68.0 \\ {[\emptyset 2.68]} \end{gathered}$ | $\begin{gathered} \varnothing 22.0 \\ {[\varnothing 0.87]} \end{gathered}$ | $\begin{gathered} \text { Ø90.0 } \\ {[\emptyset 3.54]} \end{gathered}$ | $\begin{gathered} \emptyset 70.0 \\ {[\emptyset 2.76]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} \varnothing 19.0 \\ {[\varnothing 0.75]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 13 \end{gathered}$ | $\begin{gathered} \emptyset 80.0 \\ {[\varnothing 3.15]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 12 \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ |
| $\begin{aligned} & \text { PGA120-05A6 } \\ & \text { PGA120-10A6 } \end{aligned}$ | $\begin{aligned} & 225.0 \\ & {[8.86]} \end{aligned}$ | $\begin{gathered} 180.0 \\ {[7.09]} \end{gathered}$ | $\begin{gathered} 70.0 \\ {[2.76]} \end{gathered}$ | $\begin{gathered} 9.0 \\ {[0.35]} \end{gathered}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[\varnothing 4.72]} \end{aligned}$ | $\begin{gathered} \emptyset 90.0 \\ {[Ø 3.54]} \end{gathered}$ | $\begin{gathered} \emptyset 32.0 \\ {[\varnothing 1.26]} \end{gathered}$ | $\begin{aligned} & \varnothing 200.0 \\ & {[\varnothing 7.87]} \end{aligned}$ | $\begin{aligned} & \varnothing 114.0 \\ & {[\varnothing 4.49]} \end{aligned}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ | $\begin{aligned} & \emptyset 35.0^{*} \\ & {[\varnothing 1.38]} \end{aligned}$ | $\begin{gathered} \text { M12- } \\ 1.75 \times 25 \end{gathered}$ | $\begin{aligned} & \varnothing 108.0 \\ & {[\varnothing 4.25]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 16 \end{gathered}$ | $\begin{gathered} 10.0 \\ {[0.39]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ |
| PGA120-15A4 PGA120-25A4 | $\begin{aligned} & 231.5 \\ & {[9.11]} \end{aligned}$ | $\begin{aligned} & 100.0 \\ & {[3.94]} \end{aligned}$ | $\begin{gathered} 70.0 \\ {[2.76]} \end{gathered}$ | $\begin{gathered} 9.0 \\ {[0.35]} \end{gathered}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[04.72]} \end{aligned}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \varnothing 32.0 \\ {[Ø 1.26]} \end{gathered}$ | [Ø4.53] | $\begin{gathered} \emptyset 95.0 \\ {[\emptyset 3.74]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ | $\begin{aligned} & \varnothing 22.0 \text { * } \\ & {[\varnothing 0.87]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 17 \end{gathered}$ | $\begin{aligned} & \varnothing 108.0 \\ & {[Ø 4.25]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 16 \end{gathered}$ | $\begin{gathered} 10.0 \\ {[0.39]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ |
| PGA120-15A5 PGA120-25A5 | $\begin{aligned} & 231.5 \\ & {[9.11]} \\ & \hline \end{aligned}$ | $\begin{aligned} & 130.0 \\ & {[5.12]} \end{aligned}$ | $\begin{gathered} 70.0 \\ {[2.76]} \end{gathered}$ | $\begin{gathered} 9.0 \\ {[0.35]} \\ \hline \end{gathered}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[\varnothing 4.72]} \end{aligned}$ | $\begin{gathered} \not 090.0 \\ {[Ø 3.54]} \end{gathered}$ | $\begin{gathered} \varnothing 32.0 \\ {[\varnothing 1.26]} \end{gathered}$ | $\begin{aligned} & \varnothing 145.0 \\ & {[\varnothing 5.71]} \end{aligned}$ | $\begin{aligned} & 0110.0 \\ & {[\emptyset 4.33]} \end{aligned}$ | $\begin{gathered} 8.0 \\ {[0.31]} \\ \hline \end{gathered}$ | $\begin{aligned} & \emptyset 22.0^{*} \\ & {[\varnothing 0.87]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 17 \end{gathered}$ | $\begin{aligned} & \varnothing 108.0 \\ & {[\varnothing 4.25]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 16 \end{gathered}$ | $\begin{gathered} 10.0 \\ {[0.39]} \\ \hline \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ |
| PGA155-10A6 | $\begin{gathered} 264.0 \\ {[10.39]} \end{gathered}$ | $\begin{aligned} & 180.0 \\ & {[7.09]} \end{aligned}$ | $\begin{gathered} 97.0 \\ {[3.82]} \end{gathered}$ | $\begin{gathered} 12.0 \\ {[0.47]} \end{gathered}$ | $\begin{aligned} & \varnothing 155.0 \\ & {[\varnothing 6.10]} \end{aligned}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[\varnothing 4.72]} \end{aligned}$ | $\begin{gathered} \varnothing 40.0 \\ {[\varnothing 1.57]} \end{gathered}$ | $\begin{aligned} & \varnothing 200.0 \\ & {[\varnothing 7.87]} \end{aligned}$ | $\begin{gathered} \varnothing 114.0 \\ {[\varnothing 4.49]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ | $\begin{aligned} & \varnothing 35.0^{*} \\ & {[\varnothing 1.38]} \end{aligned}$ | $\begin{array}{\|c\|} \hline \text { M12- } \\ 1.75 \times 25 \\ \hline \end{array}$ | $\begin{aligned} & \varnothing 140.0 \\ & {[\varnothing 5.51]} \end{aligned}$ | $\begin{gathered} \mathrm{M} 10- \\ 1.50 \times 28 \end{gathered}$ | $\begin{gathered} 12.0 \\ {[0.47]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ |
| PGA155-15A6 PGA155-25A6 | $\begin{gathered} 298.5 \\ {[11.75]} \end{gathered}$ | $\begin{aligned} & 180.0 \\ & {[7.09]} \end{aligned}$ | $\begin{gathered} 97.0 \\ {[3.82]} \end{gathered}$ | $\begin{gathered} 12.0 \\ {[0.47]} \end{gathered}$ | $\begin{aligned} & \varnothing 155.0 \\ & {[Ø 6.10]} \end{aligned}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[\varnothing 4.72]} \end{aligned}$ | $\begin{gathered} \emptyset 40.0 \\ {[\varnothing 1.57]} \end{gathered}$ | $\begin{aligned} & \varnothing 200.0 \\ & {[\varnothing 7.87]} \end{aligned}$ | $\begin{aligned} & \varnothing 114.0 \\ & {[\emptyset 4.49]} \end{aligned}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ | $\begin{aligned} & \boxed{05.0^{*}} \\ & {[\varnothing 1.38]} \end{aligned}$ | $\begin{gathered} \mathrm{M} 12- \\ 1.75 \times 25 \end{gathered}$ | $\begin{aligned} & \varnothing 140.0 \\ & {[\varnothing 5.51]} \end{aligned}$ | $\begin{gathered} \text { M10- } \\ 1.50 \times 28 \end{gathered}$ | $\begin{gathered} 12.0 \\ {[0.47]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ |
| * Dimension with supplied bushing |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| NOTE: See our website: www.AutomationDirect.com for complete engineering drawings. |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

## Suregear Precision Servo Gearboxes

Pricing \& Specifications - Right-Angle Shaft PGB Series


## Sure節ear Precision Servo Gearboxes

## Dimensions - Right-Angle Shaft PGB Series



SureGear PGB Series Right-Angle Shaft Gearboxes Dimension Drawing

Sureteare Precision Servo tearhox Dimensions - Right-Angle Shaft PGA Series (dimensions = mm [in] )

| Part Number | A | B | C | E | G | H | $J$ | $K$ | L | M | $N$ | P | 0 | $R$ | $S$ | $T$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { PGBO70-05A1 } \\ & \text { PGB070-10A1 } \end{aligned}$ | $\begin{aligned} & 151.5 \\ & {[5.96]} \end{aligned}$ | $\begin{array}{\|c\|} \hline 52.0 \\ {[2.05]} \end{array}$ | $\begin{aligned} & 36.0 \\ & {[1.42]} \end{aligned}$ | $\left[\begin{array}{c} 5.0 \\ {[0.20]} \end{array}\right.$ | $\begin{gathered} 670.0 \\ {[\varnothing 2.76]} \end{gathered}$ | $\begin{gathered} \emptyset 52.0 \\ {[\varnothing 2.05]} \end{gathered}$ | $\left[\begin{array}{c} 016.0 \\ {[00.63]} \end{array}\right.$ | $\begin{gathered} \varnothing 646.0 \\ {[\varnothing 1.81]} \end{gathered}$ | $\begin{gathered} \boxed{830.0} \\ {[81.18]} \end{gathered}$ | $\left[\begin{array}{c} 5.0 \\ {[0.20]} \end{array}\right.$ | $\begin{gathered} \hline 88.0 \\ {[\varnothing 0.31]} \end{gathered}$ | $\begin{gathered} \text { M4- } \\ 0.7 \times 9 \end{gathered}$ | $\begin{gathered} \varnothing 662.0 \\ {[\varnothing 2.44]} \end{gathered}$ | $\begin{gathered} \text { M5- } \\ 0.8 \times 10 \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ | $\begin{gathered} 5.0 \\ {[0.20]} \end{gathered}$ |
| $\begin{aligned} & \text { PGBO70-05A2 } \\ & \text { PGBO70-10A2 } \end{aligned}$ |  | $\begin{array}{\|c\|} \hline 65.0 \\ {[2.56]} \end{array}$ |  |  |  |  |  | $\begin{gathered} \varnothing 870.0 \\ {[\varnothing 2.76]} \end{gathered}$ | $\begin{gathered} \varnothing 650.0 \\ {[\varnothing 1.97]} \end{gathered}$ |  | $\begin{array}{\|c} \hline \varnothing 14.0 \\ {[\varnothing 0.55]} \end{array}$ | $\begin{array}{r} \text { M5- } \\ 0.8 \times 11 \end{array}$ |  |  |  |  |
| $\begin{aligned} & \text { PGBO70-15A1 } \\ & \text { PGB070-25A1 } \end{aligned}$ | $\begin{aligned} & 158.0 \\ & {[6.22]} \end{aligned}$ | $\begin{array}{\|c\|} \hline 52.0 \\ {[2.05]} \\ \hline \end{array}$ |  |  |  |  |  | $\begin{gathered} 046.0 \\ {[\varnothing 1.81]} \end{gathered}$ | $\begin{gathered} \boxed{830.0} \\ {[81.18]} \end{gathered}$ |  | $\begin{gathered} \boxed{98.0} \\ {[\varnothing 0.31]} \end{gathered}$ | $\begin{gathered} \text { M4- } \\ 0.7 \times 9 \end{gathered}$ |  |  |  |  |
| $\begin{aligned} & \text { PGBO70-15A2 } \\ & \text { PGBO70-25A2 } \end{aligned}$ | $\begin{aligned} & 163.5 \\ & {[6.44]} \end{aligned}$ | $\begin{gathered} 65.0 \\ {[2.56]} \end{gathered}$ |  |  |  |  |  |  |  |  | ø14.0 | M5- |  |  |  |  |
| $\begin{aligned} & \text { PGB090-15A2 } \\ & \text { PGB090-25A2 } \end{aligned}$ | $\begin{aligned} & \hline 204.5 \\ & {[8.05]} \end{aligned}$ |  | $\begin{gathered} 46.0 \\ {[1.81]} \end{gathered}$ | $\begin{array}{\|c\|c} 7.0 \\ {[0.28]} \end{array}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \emptyset 68.0 \\ {[\varnothing 2.68]} \end{gathered}$ | $\begin{gathered} \emptyset 22.0 \\ {[\varnothing 0.87]} \end{gathered}$ | [Ø2.76] | [01.97] |  | [ø0.55] | $0.8 \times 11$ | $\begin{gathered} 980.0 \\ {[\varnothing 3.15]} \end{gathered}$ | $\begin{gathered} \text { M6- } \\ 1.0 \times 12 \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ | $\begin{gathered} 6.0 \\ {[0.24]} \end{gathered}$ |
| $\begin{aligned} & \text { PGB090-05A3 } \\ & \text { PGB090-10A3 } \end{aligned}$ | $\begin{aligned} & 205.5 \\ & {[8.09]} \end{aligned}$ | $\begin{gathered} 80.0 \\ {[3.15]} \end{gathered}$ |  |  |  |  |  |  | 070.0 | 6.0 | ø19.0 | M6- |  |  |  |  |
| $\begin{aligned} & \text { PGB090-15A3 } \\ & \text { PGB090-25A3 } \end{aligned}$ | $\begin{aligned} & 210.5 \\ & {[8.29]} \end{aligned}$ |  |  |  |  |  |  | [03.54] | [ø2.76] | [0.24] | [ø0.75] | 1.0x13 |  |  |  |  |
| $\begin{aligned} & \text { PGB090-05A4 } \\ & \text { PGB090-10A4 } \end{aligned}$ | $\begin{aligned} & 205.5 \\ & {[8.09]} \end{aligned}$ | 100.0 |  |  |  |  |  | 0115.0 |  | $\left\lvert\, \begin{gathered} 8.0 \\ {[0.31]} \end{gathered}\right.$ | $\begin{aligned} & \varnothing 22.0^{*} \\ & {[\varnothing 0.87]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 17 \end{gathered}$ |  |  |  |  |
| $\begin{aligned} & \text { PGB120-15A4 } \\ & \text { PGB120-25A4 } \end{aligned}$ | $\begin{aligned} & 272.0 \\ & {[10.71]} \end{aligned}$ | [3.94] | $\left[\begin{array}{c} 70.0 \\ {[2.76]} \end{array}\right.$ | $\begin{gathered} 9.0 \\ {[0.35]} \end{gathered}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[\varnothing 4.72]} \end{aligned}$ | $\begin{gathered} \varnothing 90.0 \\ {[\varnothing 3.54]} \end{gathered}$ | $\begin{gathered} \varnothing 32.0 \\ {[\varnothing 1.26]} \end{gathered}$ | [04.53] | [03.74] |  |  |  | $\begin{aligned} & \varnothing 108.0 \\ & {[\varnothing 4.25]} \end{aligned}$ | $\begin{gathered} \text { M8- } \\ 1.25 \times 16 \end{gathered}$ | $\begin{gathered} 10.0 \\ {[0.39]} \end{gathered}$ | $\begin{gathered} 8.0 \\ {[0.31]} \end{gathered}$ |
| $\begin{aligned} & \text { PGB120-05A5 } \\ & \text { PGB120-10A5 } \end{aligned}$ | $\begin{aligned} & \hline 266.0 \\ & {[10.47]} \end{aligned}$ | $\begin{aligned} & 130.0 \\ & {[5.12]} \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\begin{aligned} & \text { PGB120-15A5 } \\ & \text { PGB120-25A5 } \end{aligned}$ | $\begin{aligned} & 272.0 \\ & {[10.71]} \end{aligned}$ |  |  |  |  |  |  | [05.71] | [04.33] |  |  |  |  |  |  |  |
| $\begin{array}{\|l} \text { PGB120-05A6 } \\ \text { PGB120-10A6 } \end{array}$ | $\begin{gathered} 268.5 \\ {[10.57]} \end{gathered}$ | $\begin{aligned} & 180.0 \\ & {[7.09]} \end{aligned}$ |  |  |  |  |  | $\begin{aligned} & \varnothing 200.0 \\ & {[\varnothing 7.87]} \end{aligned}$ | $\begin{aligned} & \varnothing 114.0 \\ & {[\varnothing 4.50]} \end{aligned}$ |  | $\begin{aligned} & \varnothing 35.0^{*} \\ & {[\varnothing 1.38]} \end{aligned}$ | $\begin{gathered} \text { M12- } \\ 1.75 \times 25 \end{gathered}$ |  |  |  |  |
| $\begin{aligned} & \text { PGB155-05A6 } \\ & \text { PGB155-10A6 } \end{aligned}$ | $\begin{aligned} & \hline 341.0 \\ & {[13.43]} \end{aligned}$ |  | $\begin{gathered} 97.0 \\ {[3.82]} \end{gathered}$ | $\begin{gathered} 12.0 \\ {[0.47]} \end{gathered}$ | $\begin{aligned} & \varnothing 155.0 \\ & {[\varnothing 6.10]} \end{aligned}$ | $\begin{aligned} & \varnothing 120.0 \\ & {[\varnothing 4.72]} \end{aligned}$ | $\begin{gathered} 940.0 \\ {[\varnothing 1.57]} \end{gathered}$ |  |  |  |  |  | $\begin{array}{\|l} \varnothing 140.0 \\ {[\varnothing 5.51]} \end{array}$ | $\begin{aligned} & \mathrm{M} 10- \\ & 1.5 \times 20 \end{aligned}$ | $\begin{gathered} 12.0 \\ {[0.47]} \end{gathered}$ |  |
| $\begin{aligned} & \text { PGB155-15A6 } \\ & \text { PGB155-25A6 } \end{aligned}$ | $\begin{aligned} & \hline 364.0 \\ & {[14.33]} \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

* Dimension with supplied bushing

NOTE: See our website: www.AutomationDirect.com for complete engineering drawings

## Sure筥ear Precision Servo Gearboxes

## SureGear ${ }^{\circledR}$ Servo Gearbox Replacement Parts



## SureGear® Precision Servo Gearboxes - Replacement Parts

| Part Number | Price | Description |
| :--- | ---: | :--- |
| PG050-KEY | $\$ 4.00$ | Output Shaft Key, replacement, $4 \times 4 \times 14 \mathrm{~mm}$, for SureGear PGA050 series gearboxes. |
| PG070-KEY | $\$ 4.00$ | Output Shaft Key, replacement, $5 \times 5 \times 22 \mathrm{~mm}$, for SureGear PGA070 and PGB070 series gearboxes. |
| PG090-KEY | $\$ 4.00$ | Output Shaft Key, replacement, $6 \times 6 \times 28 \mathrm{~mm}$, for SureGear PGA090 and PGB090 series gearboxes. |
| PG120-KEY | $\$ 4.00$ | Output Shaft Key, replacement, $10 \times 8 \times 45 \mathrm{~mm}$, for SureGear PGA120 and PGB120 series gearboxes. |
| PG155-KEY | $\$ 4.00$ | Output Shaft Key, replacement, $12 \times 8 \times 65 \mathrm{~mm}$, for SureGear PGA155 and PGB155 series gearboxes. |
| PGA4-A5-BUSH | $\$ 19.00$ | Input Shaft Bushing, replacement, $28 \times 22 \times 30.5 \mathrm{~mm}$, for all SureGear gearboxes using SVL-210(B) and SVM-210(B) SureServo motors. |
| PGA6-BUSH | $\$ 19.00$ | Input Shaft Bushing, replacement, $38 \times 35 \times 36 \mathrm{~mm}$, for all SureGear gearboxes using SVM-220(B) and SVM-230(B) SureServo motors. |


[^0]:    * Same day shipping with approved company credit or credit card. Free 2-day (transit) shipping for orders over \$49; other expedited services extra. See Web site or catalog Terms and Conditions for all details and exceptions.

